

Computer Vision 2011: Proposed Projects (titles are paraphrased)

Registration and Detection in Array of Overhead Cameras

Richard Otap

Puskar Naha

Henry Duwe

Autonomous Helicopter Navigation using Vanishing Points, Object Detection

Young Min Ahn

De-noise, improve spatial resolution, perform segmentation for classes of FTIR Spectroscopy Data

Tan Nguyen

Visual Saliency Engine Based on Social Interaction

Logan Niehaus

GPU Implementation of Deformable Object Detection

Daniel Liu

Compressive Inverse Light Transport

Xinqi Chu

Prediction of Gaze on Web Cams

Rohit Naini, Honghai Yu

Hardware implementation of graph cuts and stereo

Shang-nien Tsai, Jungwook Choi

Recover body shape and pose using Kinect sensor

Prateek Rungta

Cross-Category Knowledge Propagation for Learning Visual Concepts

GuoJun Qi

Shape-based Recognition

Saeed Maleki

Region-based recognition (group superpixels into objects)

Jia-bin Huang

Tracking tennis court and ball

Daniel Wolf and Rasmus Simander

Detecting Text in Natural Scenes

Cheng-Wei Lee

Multiple proposals

Quirin Scheitle and Tim Schack

Use image segmentation to improve Kinect depth maps and vice versa

Ammar Hussein and Adbul Dakkak

GPU implementation of deformable part detector

Daniel Liu