

## CS477 Formal Software Development Methods

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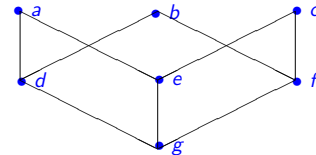
Slides based in part on previous lectures by Mahesh Vishwanathan, and by Gul Agha

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## Partial orders and Complete Lattices

A **partial order** on a set  $S$  is a binary relation  $\leq$  on  $S$  such that

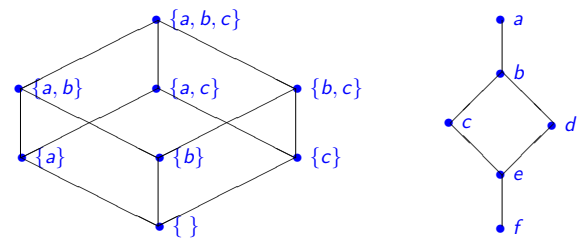
- **[Ref]**  $s \leq s$  for all  $s \in S$
- **[Antisym]**  $s \leq t$  and  $t \leq s$  implies  $s = t$ , for all  $s, t \in S$
- **[Trans]**  $s \leq t$  and  $t \leq u$  implies  $s \leq u$ , for all  $s, t, u \in S$



## Upper Bounds and Complete Lattices

- In a partial order  $(S, \leq)$ , given  $X \subseteq S$ ,  $y$  is an **upper bound** for  $X$  if for all  $x \in X$  we have  $x \leq y$ .
- $y$  is a **least** upper bound of  $X$ ,  $y$  is an upper bound of  $X$  and whenever  $z$  is an upper bound of  $X$ ,  $y \leq z$ .
- **Note:** Least upper bounds are unique.
- A **complete lattice** is a partial order  $(L, \leq)$  such that for all  $X \subseteq S$  there exists a (unique) least upper bound.
- Write  $\text{lub}(X)$  or  $\bigvee X$  for the least upper bound of  $X$ .
- Write  $x \vee y$  for  $\bigvee\{x, y\}$
- **Note:**  $x \vee y = x \iff y \leq x$
- **Note:** Given a set  $S$ ,  $(\mathcal{P}(S), \subseteq)$  is a complete lattice.
- Write  $\perp = \bigvee\{\}$  and  $\top = \text{bigvee}S$

## Example Complete Lattices



## Control-Flow Graphs

A **Control-Flow Graph** is a tuple  $(N, E, l, k)$  where

- $N$  is a finite set of nodes
- $l: N \rightarrow \{\text{Entry}, \text{Exit}, i := e, \text{if } b, \}$
- $E \subseteq N \times N$  such that
  - for all  $m \in N$  we have  $|\{(n, (m, n)) \in E\}| \leq 2$
  - if  $m \in N$  and  $l(m) = \text{Exit}$  then  $|\{(n, (m, n)) \in E\}| = 0$
  - if  $m \in N$  and  $l(m) = \text{Entry}$  or  $l(m) = i := e$  for some identifier  $i$  and expression  $e$ , then  $|\{(n, (m, n)) \in E\}| = 1$
  - if  $m \in N$  and  $l(m) = \text{if } b$  for some boolean expression  $b$ , then  $|\{(n, (m, n)) \in E\}| = 2$
- $k: E \rightarrow \{\text{seq}, \text{yes}, \text{no}\}$  such that
  - if  $(m, n) \in E$  and  $l(m) = \text{Entry}$  or  $l(m) = i := e$ , then  $k((m, n)) = \text{seq}$
  - if  $m \in N$  and  $l(m) = \text{if } b$ , then  $\{k((m, n)).(m, n) \in E\} = \{\text{yes}, \text{no}\}$

## Environments Revisited

Previously: **environments** are *partial* functions from identifiers ( $\text{Ident}$ ) to values.

Add to usual values two new constants:  $\text{Values} = \{v \mid v \text{ a value}\} \cup \{\top, \perp\}$ .

$\perp$  means undefined

$\top$  means error

Order Values by  $v_1 \leq v_2$  implies  $v_1 = v_2$ , and  $\perp \leq v$  and  $v \leq \top$  for all values  $v, v_1, v_2$

Redefine  $\text{Env} = \text{Ident} \rightarrow \text{Values}$ , all *total* functions from identifiers to extended values

Can view every old environment as an element of  $\text{Env}$

Fix control flow graph  $G = (N, E, I, k)$

$States = E \times Env$

Note: Entry is never the label on node on the end of the edge in a state.

Can define **next state** of state  $s \in States$ : only need the end state of the edge and the environment.

**next state** is a transition relation.

From **next state** can define a run.