CS477 Formal Software Development Methods

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Labeled Transition System (LTS)

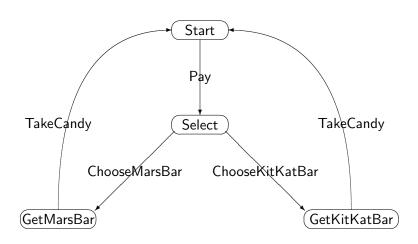
A labeled transition system (LTS) is a 4-tuple (Q, Σ, δ, I) where

- Q set of states
 - Q finite or countably infinite
- ∑ set of labels (aka actions)
 - Σ finite or countably infinite
- $\delta \subseteq Q \times \Sigma \times Q$ transition relation
- $I \subseteq Q$ initial states

Note: Write $q \xrightarrow{\alpha} q'$ for $(q, \alpha, q') \in \delta$.

Example: Candy Machine

Example: Candy Machine



Predecessors, Successors and Determinism

Let (Q, Σ, δ, I) be a labeled transition system.

$$ln(q, \alpha) = \{q' | q' \xrightarrow{\alpha} q\} \qquad ln(q) = \bigcup_{\alpha \in \Sigma} ln(q, \alpha)$$

$$Out(q, \alpha) = \{q' | q \xrightarrow{\alpha} q'\} \quad Out(q) = \bigcup_{\alpha \in \Sigma} Out(q, \alpha)$$

A labeled transstion system (Q, Σ, δ, I) is deterministic if

$$|I| \leq 1$$
 and $|Out(q, lpha)| \leq 1$

Labeled Transition Systems vs Finite State Automata

- LTS have no accepting states
 - Every FSA an LTS just forget the accepting states
- Set of states and actions may be countably infinite
- May have infinite branching

Exections, Traces, and Runs

- A partial exection is a finite or infinite alternating sequence of states and actions $\rho = q_0 \alpha_1 q_1 \dots \alpha_n q_n \dots$ such that
 - $q_0 \in I$
 - $q_{i-1} \xrightarrow{\alpha_i} q_i$ for all i with q_i in sequence
- An exection is a maxial partial exection
- A finite or infinite sequence of actions $\alpha_1 \dots \alpha_n \dots$ is a trace if there exist states $q_0 \dots q_n \dots$ such that the sequence $q_0 \alpha_1 q_1 \dots \alpha_n q_n \dots$ is a partial execution.
 - Let $\rho = q_0 \alpha_1 q_1 \dots \alpha_n q_n \dots$ be a partial execution. Then $trace(\rho) = \alpha_1 \dots \alpha_n \dots$

A finite or inifnite sequence of states $q_0 \ldots q_n \ldots$ is a run if there exist actions $\alpha_1 \ldots \alpha_n \ldots$ such that the sequence $q_0 \alpha_1 q_1 \ldots \alpha_n q_n \ldots$ is a partial execution.

• Let $\rho = q_0 \alpha_1 q_1 \dots \alpha_n q_n \dots$ be a partial execution. Then $run(\rho) = q_0 \dots q_n \dots$



Example: Candy Machine

- Partial execution:
 - $\rho = \mathit{Start} \cdot \mathit{Pay} \cdot \mathit{Select} \cdot \mathit{ChooseMarsBar} \cdot \mathit{GetMarsBar} \cdot \mathit{TakeCandy} \cdot \mathit{Start}$
- Trace: $trace(\rho) = Pay \cdot ChooseMarsBar \cdot TakeCandy$
- Run: $run(\rho) = Start \cdot Select \cdot GetMarsBar \cdot Start$

Program Transition System

A Program Transition System is a triple (S, T, init)

- $S = (\mathcal{G}, \mathcal{D}, \mathcal{F}, \phi, \mathcal{R}, \rho)$ is a first-order structure over signature $\mathcal{G} = (V, F, af, R, ar)$, used to interpret expressions and conditionals
- T is a finite set of conditional transitions of the form

$$g \rightarrow (v_1, \ldots, v_n) := (e_1, \ldots, e_n)$$

where $v_i \in V$ distinct, and e_i term in \mathcal{G} , for $i = 1 \dots n$

init initial condition asserted to be true at start of program

Example: Traffic Light

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V = \{Turn, NSColor, EWColor\}, F = \{NS, EW, Red, Yellow, Green\} (all
arity 0), R = \{=\}
T = Turn = NS \land NSColor = Red \rightarrow NSColor := Green
                  NSColor = Green \rightarrow NSColor := Yellow
                 NSColor = Yellow \rightarrow (Turn, NSColor) := (EW, Red)
    Turn = EW \land EWColor = Red \rightarrow EWColor := Green
                 EWColor = Green \rightarrow EWColor := Yellow
                 EWColor = Yellow \rightarrow (Turn, EWColor) := (NS, Red)
init = (NSColor = Red \land EWColor = Red \land (Turn = NS \lor Turn = EW)
```

Mutual Exclusion (Attempt)

Mutual Exclusion PTS

$$V = \{pc1, pc2, c1, c2\}, F = \{m1, \dots, m6, n1, \dots, n6, 0, 1\}$$

$$T = pc1 = m1 \rightarrow pc1 := m2$$

$$pc1 = m3 \rightarrow (pc1, c1) := (m4, 0)$$

$$pc1 = m4 \land c2 = 1 \text{ to } pc1 := m5$$

$$pc1 = m5 \rightarrow pc1 := m6$$

$$pc1 = m6 \rightarrow (pc1, c1) := (m1, 1)$$

$$pc2 = n1 \rightarrow pc2 := n2$$

$$pc2 = n2 \rightarrow pc2 := n3$$

$$pc2 = n3 \rightarrow (pc2, c2) := (n4, 0)$$

$$pc2 = n4 \land c1 = 1 \text{ to } pc2 := n5$$

$$pc2 = n6 \rightarrow (pc2, c2) := (n1, 1)$$

$$init = (pc1 = m1 \land pc2 = n1 \land c1 = 1 \land c2 = 1)$$

Interpreting PTS as LTS

Let (S, T, init) be a program transition system. Assume V finite, \mathcal{D} at most countable.

- ullet Let $Q=V imes \mathcal{D}$, interpretted as all assingments of values to variables
 - Can restrict to pairs (v, d) where v and d have same type
- Let $\sigma = T$
- Let $\delta(q, g \to (v_1, \dots, v_n) := (e_1, \dots, e_n), q') = M_q(g) \land q'(v) = \begin{cases} T_q(e_i) & \text{if } v = v_1 \text{ some } i \leq n \\ q(v) & \text{otherwise} \end{cases}$
- $I = \{q | \mathcal{T}_q(init) = \mathbf{T}\}$

Examples (cont)

- LTS for traffic light has $3 \times 3 \times 2 = 18$ possible well typed states
 - Is is possible to reach a state where NSColor ≠ Red ∧ EWColor ≠ Red from an initial state?
 - If so, what sequence of actions alows this?
 - Do all the immediate predecessors of a state where *NSColor* = *Green* ∨ *EWColor* = *Green* satisfy *NSColor* = *Red* ∧ *EWColor* = *Red*?
 - If not, are any of those offend states reachable from and initial state, and if so, how?
- LTS for Mutual Exclusion has $6 \times 6 \times 2 \times 2 = 144$ posible well-tped states.
 - Is is possible to reach a state where $pc1 = m5 \land pc2 = n5$?
- How can we state these questions rigorously, formally?
- Cna we find an algorihm to answer these types of questions?



Linear Temporal Logic - Syntax

$$\varphi ::= p|(\varphi)| \not p|\varphi \wedge \varphi'|\varphi \vee \varphi'$$
$$| \circ \varphi|\varphi \mathcal{U} \varphi'|\varphi \mathcal{V} \varphi'|\Box \varphi| \Diamond \varphi$$

- p − a propostion over state variables
- $\circ \varphi$ "next"
- $\varphi \mathcal{U} \varphi'$ "until"
- $\varphi \mathcal{V} \varphi'$ "releases"
- $\Box \varphi$ "box", "always", "forever"
- $\Diamond \varphi$ "diamond", "eventually", "sometime"

LTL Semantics: The Idea

Formal LTL Semantics

Given:

- $\mathcal{G} = (V, F, af, R, ar)$ signature expressing state propositions
- Q set of states,
- \mathcal{M} modeling function over Q and cG: cM(q, p) is true iff q models p. Write $q \models p$.
- $\sigma = q_0 q_1 \dots q_n \dots$ infinite sequence of state from Q.
- $sigma^i = q_i q_{i+1} \dots q_n \dots$ the i^{th} tail of σ

Say σ models LTL formula φ , write $\sigma \models \varphi$ as follows:

- $\sigma \models p$ iff $q_0 \models p$
- $\sigma \models \neg \varphi$ iff $\sigma \not\models \varphi$
- $\sigma \models \varphi \land \psi$ iff $\sigma \models \varphi$ and $\sigma \models \psi$.
- $\sigma \models \varphi \lor \psi$ iff $\sigma \models \varphi$ or $\sigma \models \psi$.
- $\bullet \ \sigma \models \circ \varphi \ \text{iff} \ \sigma^1 \models \varphi$
- $\sigma \models \varphi \mathcal{U} \psi$ iff for some k, $\sigma^k \models \psi$ and for all $i \leq k$, $\sigma^i \models \varphi$
- $\sigma \models \varphi V \psi$ iff for some k, $\sigma^k \models \varphi$ and for all i < k, $\sigma^i \models \psi$, or for all i, $\sigma^i \models \psi$.