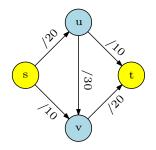
### CS 473: Fundamental Algorithms, Spring 2013

# **Network Flow Algorithms**

Lecture 17 March 27, 2013

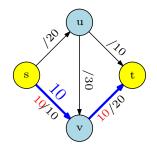
# Part I

# Algorithm(s) for Maximum Flow



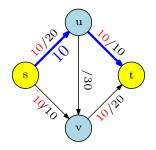
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**Augment** flow along this path.



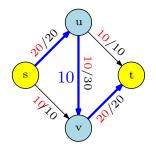
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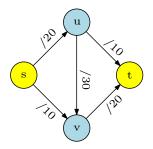
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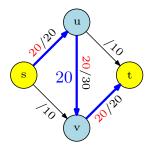


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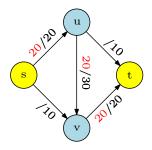
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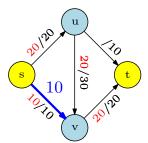
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  - Repeat augmentation for as long as possible.



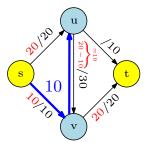
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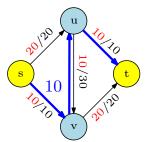
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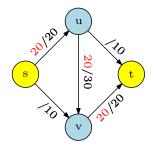
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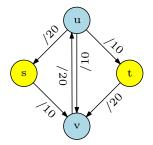
#### Definition

For a network G = (V, E) and flow f, the residual graph  $G_f = (V', E')$  of G with respect to f is

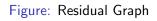
- V' = V,
- **2** Forward Edges: For each edge  $e \in E$  with f(e) < c(e), we add  $e \in E'$  with capacity c(e) f(e).
- **3** Backward Edges: For each edge  $e = (u, v) \in E$  with f(e) > 0, we add  $(v, u) \in E'$  with capacity f(e).

### Residual Graph Example





# Figure: Flow on edges is indicated in red



**Observation:** Residual graph captures the "residual" problem exactly.

#### Lemma

Let **f** be a flow in **G** and **G**<sub>f</sub> be the residual graph. If **f**' is a flow in **G**<sub>f</sub> then  $\mathbf{f} + \mathbf{f}'$  is a flow in **G** of value  $\mathbf{v}(\mathbf{f}) + \mathbf{v}(\mathbf{f}')$ .

#### Lemma

Let **f** and **f'** be two flows in **G** with  $\mathbf{v}(\mathbf{f'}) \ge \mathbf{v}(\mathbf{f})$ . Then there is a flow **f''** of value  $\mathbf{v}(\mathbf{f'}) - \mathbf{v}(\mathbf{f})$  in **G**<sub>f</sub>.

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### Residual Graph Property: Implication

*Recursive* algorithm for finding a maximum flow:

```
\begin{array}{l} MaxFlow(G,s,t):\\ \mbox{ if the flow from s to t is 0 then }\\ \mbox{ return 0 }\\ \mbox{ Find any flow f with } v(f) > 0 \mbox{ in } G\\ \mbox{ Recursively compute a maximum flow } f' \mbox{ in } G_f\\ \mbox{ Output the flow } f + f' \end{array}
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*Iterative* algorithm for finding a maximum flow:

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\begin{split} & \mathsf{MaxFlow}\left(G,s,t\right):\\ & \text{Start with flow } f \text{ that is } 0 \text{ on all edges}\\ & \text{while there is a flow } f' \text{ in } G_f \text{ with } \nu(f') > 0 \text{ do}\\ & f = f + f'\\ & \text{Update } G_f \end{split}
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\begin{array}{l} algFordFulkerson \\ for every edge e, f(e) = 0 \\ G_f \text{ is residual graph of } G \text{ with respect to } f \\ while \; G_f \text{ has a simple s-t path } do \\ let \; P \; be \; simple \; s\text{-t path in } G_f \\ f = augment(f, P) \\ Construct \; new \; residual \; graph \; G_f. \end{array}
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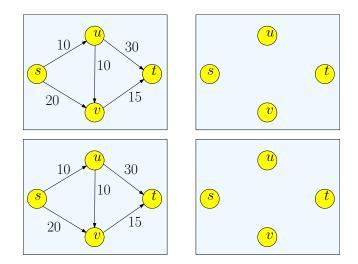
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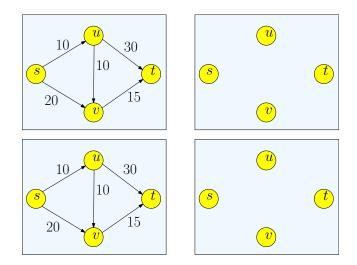
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# Example

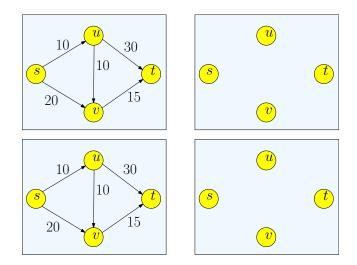


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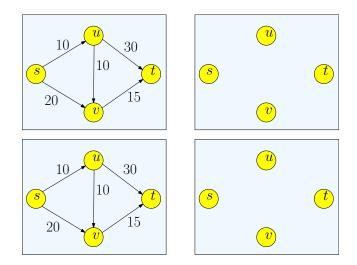
### Example continued



### Example continued



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#### Lemma

If f is a flow and P is a simple s-t path in  $G_f$ , then f' = augment(f, P) is also a flow.

#### Proof.

Verify that f' is a flow. Let b be augmentation amount.

• Capacity constraint: If  $(u, v) \in P$  is a forward edge then f'(e) = f(e) + b and  $b \leq c(e) - f(e)$ . If  $(u, v) \in P$  is a backward edge, then letting e = (v, u), f'(e) = f(e) - b and  $b \leq f(e)$ . Both cases  $0 \leq f'(e) \leq c(e)$ .

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- Conservation constraint: Let v be an internal node. Let e<sub>1</sub>, e<sub>2</sub> be edges of P incident to v. Four cases based on whether e<sub>1</sub>, e<sub>2</sub> are forward or backward edges. Check cases (see fig next slide).

#### Properties of Augmentation Conservation Constraint

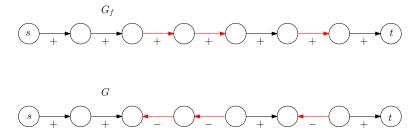


Figure: Augmenting path P in  $G_f$  and corresponding change of flow in G. Red edges are backward edges.

#### Lemma

At every stage of the Ford-Fulkerson algorithm, the flow values on the edges (i.e., f(e), for all edges e) and the residual capacities in  $G_f$  are integers.

#### Proof.

Initial flow and residual capacities are integers. Suppose lemma holds for **j** iterations. Then in (j + 1)st iteration, minimum capacity edge **b** is an integer, and so flow after augmentation is an integer.

# Progress in Ford-Fulkerson

#### Proposition

Let f be a flow and f' be flow after one augmentation. Then  $\nu(f) < \nu(f').$ 

#### Proof.

Let P be an augmenting path, i.e., P is a simple s-t path in residual graph. We have the following.

- First edge e in P must leave s.
- Original network G has no incoming edges to s; hence e is a forward edge.
- **P** is simple and so never returns to **s**.
- Thus, value of flow increases by the flow on edge e.

# Termination proof for integral flow

#### Theorem

Let **C** be the minimum cut value; in particular  $C \leq \sum_{e \text{ out of } s} c(e)$ . Ford-Fulkerson algorithm terminates after finding at most **C** augmenting paths.

#### Proof.

The value of the flow increases by at least 1 after each augmentation. Maximum value of flow is at most  ${\sf C}.$ 

#### Running time

- Number of iterations  $\leq C$ .
- 2 Number of edges in  $G_f \leq 2m$ .
- Solution Time to find augmenting path is O(n + m).

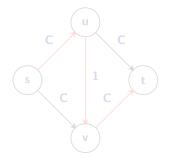
• Running time is O(C(n + m)) (or O(mC)).

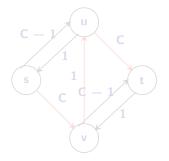
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### Efficiency of Ford-Fulkerson

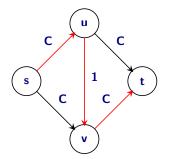
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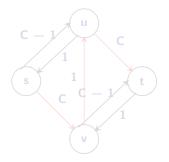




Ford-Fulkerson can take  $\Omega(C)$  iterations.

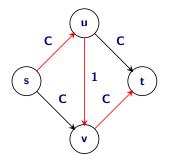
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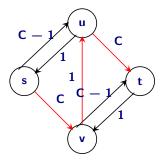




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## Question: When the algorithm terminates, is the flow computed the maximum **s-t** flow?

Proof idea: show a cut of value equal to the flow. Also shows that maximum flow is equal to minimum cut!

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## **Recalling Cuts**

### Definition

Given a flow network an s-t cut is a set of edges  $\mathbf{E}' \subset \mathbf{E}$  such that removing  $\mathbf{E}'$  disconnects s from t: in other words there is no directed  $\mathbf{s} \to \mathbf{t}$  path in  $\mathbf{E} - \mathbf{E}'$ . Capacity of cut  $\mathbf{E}'$  is  $\sum_{e \in \mathbf{F}'} \mathbf{c}(\mathbf{e})$ .

Let  $\mathbf{A} \subset \mathbf{V}$  such that

 $\textbf{0} \ \textbf{s} \in \textbf{A}, \textbf{t} \not\in \textbf{A}, \text{ and}$ 

**2**  $\mathbf{B} = \mathbf{V} \setminus -\mathbf{A}$  and hence  $\mathbf{t} \in \mathbf{B}$ .

Define  $(A, B) = \{(u, v) \in E \mid u \in A, v \in B\}$ 

### Claim

(A, B) is an s-t cut.

Recall: Every minimal s-t cut E' is a cut of the form (A, B).

### Lemma

If there is no s-t path in  $G_f$  then there is some cut (A,B) such that v(f)=c(A,B)

### Proof.

Let **A** be all vertices reachable from **s** in  $G_f$ ; **B** = **V** \ **A**.

s ∈ A and t ∈ B. So (A, B) is an s-t cut in G.

t If  $e = (u, v) \in G$  with  $u \in A$  and  $v \in B$ , then f(e) = c(e) (saturated edge) because otherwise v is reachable from s in  $G_f$ .

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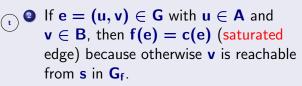
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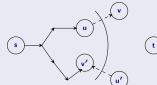
s ∈ A and t ∈ B. So (A, B) is an s-t cut in G.



### Lemma Proof Continued

### Proof.

	If $\mathbf{e} = (\mathbf{u}', \mathbf{v}') \in \mathbf{G}$ with $\mathbf{u}' \in \mathbf{B}$ and $\mathbf{v}' \in \mathbf{A}$ , then $\mathbf{f}(\mathbf{e}) = 0$ because
	otherwise $\mathbf{u}'$ is reachable from $\mathbf{s}$ in $\mathbf{G}_{\mathbf{f}}$
v	O Thus,
	(t) $v(f) = f^{out}(A) - f^{in}(A)$



- $\begin{array}{rcl} (f) & = & f^{\rm out}(A) f^{\rm in}(A) \\ & = & f^{\rm out}(A) 0 \\ & = & c(A,B) 0 \end{array}$ 
  - = c(A, B).

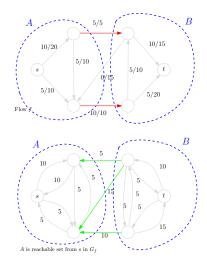
## Example

Flow f 10/10 Flow f 10/10 5/10 5/10 10/15 5/10 5/10 5/20

 $\mathbf{5}$ 

 $\overline{5}$ 

5



Residual graph  $G_f$ : no s-t path

10

5

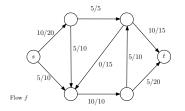
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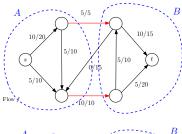
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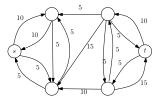
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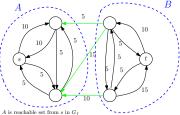
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Residual graph  $G_f$ : no s-t path



### Theorem

The flow returned by the algorithm is the maximum flow.

### Proof.

- For any flow f and s-t cut (A, B),  $v(f) \leq c(A, B)$ .
- For flow f\* returned by algorithm, v(f\*) = c(A\*, B\*) for some s-t cut (A\*, B\*).
- Hence, f\* is maximum.

# Max-Flow Min-Cut Theorem and Integrality of Flows

### Theorem

For any network **G**, the value of a maximum **s-t** flow is equal to the capacity of the minimum **s-t** cut.

### Proof.

Ford-Fulkerson algorithm terminates with a maximum flow of value equal to the capacity of a (minimum) cut.

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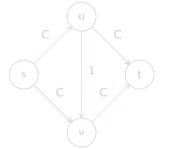
### Theorem

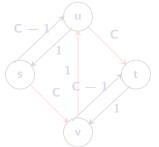
For any network **G** with integer capacities, there is a maximum **s**-**t** flow that is integer valued.

### Proof.

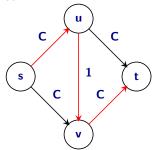
Ford-Fulkerson algorithm produces an integer valued flow when capacities are integers.

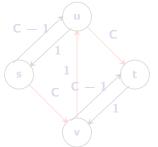
Running time = O(mC) is not polynomial. Can the upper bound be achieved?



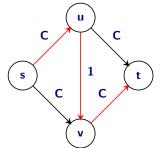


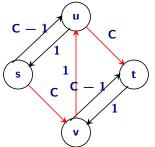
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## Polynomial Time Algorithms

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Question: Is there a variant of Ford-Fulkerson that leads to a polynomial time algorithm? Can we choose an augmenting path in some clever way? Yes! Two variants.

- ① Choose the augmenting path with largest bottleneck capacity.
- One of the shortest augmenting path.

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- Pick augmenting paths with largest bottleneck capacity in each iteration of Ford-Fulkerson.
- I How do we find path with largest bottleneck capacity?
  - **()** Assume we know  $\Delta$  the bottleneck capacity
  - Remove all edges with residual capacity  $\leq \Delta$
  - One of the content of the content
  - In Do binary search to find largest  $\Delta$
  - Running time: O(m log C)
- Can we bound the number of augmentations? Can show that in O(m log C) augmentations the algorithm reaches a max flow. This leads to an O(m<sup>2</sup> log<sup>2</sup> C) time algorithm.

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How do we find path with largest bottleneck capacity?

- Max bottleneck capacity is one of the edge capacities. Why?
- ② Can do binary search on the edge capacities. First, sort the edges by their capacities and then do binary search on that array as before.
- Algorithm's running time is O(m log m).
- Oifferent algorithm that also leads to O(m log m) time algorithm by adapting Prim's algorithm.

### Removing Dependence on C

### **O** Dinic [1970], Edmonds and Karp [1972]

- Picking augmenting paths with fewest number of edges yields a  $O(m^2n)$  algorithm, i.e., independent of C. Such an algorithm is called a strongly polynomial time algorithm since the running time does not depend on the numbers (assuming RAM model). (Many implementation of Ford-Fulkerson would actually use shortest augmenting path if they use BFS to find an s-t path).
- Further improvements can yield algorithms running in O(mn log n), or O(n<sup>3</sup>).

## Ford-Fulkerson Algorithm

```
\begin{array}{l} algEdmondsKarp \\ for every edge e, f(e) = 0 \\ G_f \text{ is residual graph of } G \text{ with respect to } f \\ while G_f \text{ has a simple } s\text{-t path } do \\ Perform BFS \text{ in } G_f \\ P: \text{ shortest } s\text{-t path in } G_f \\ f = augment(f, P) \\ Construct new residual graph } G_f. \end{array}
```

Running time  $O(m^2n)$ .

## Finding a Minimum Cut

### Question: How do we find an actual minimum s-t cut? Proof gives the algorithm!

- Compute an s-t maximum flow f in G
- **2** Obtain the residual graph  $G_f$
- Find the nodes A reachable from s in G<sub>f</sub>
- Output the cut  $(A, B) = \{(u, v) \mid u \in A, v \in B\}$ . Note: The cut is found in G while A is found in G<sub>f</sub>

Running time is essentially the same as finding a maximum flow.

Note: Given **G** and a flow **f** there is a linear time algorithm to check if **f** is a maximum flow and if it is, outputs a minimum cut. How?

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- Dinic, E. A. (1970). Algorithm for solution of a problem of maximum flow in a network with power estimation. *Soviet Math. Doklady*, 11:1277–1280.
- Edmonds, J. and Karp, R. M. (1972). Theoretical improvements in algorithmic efficiency for network flow problems. *J. Assoc. Comput. Mach.*, 19(2):248–264.