

# More Dynamic Programming

## Lecture 9

February 16, 2013

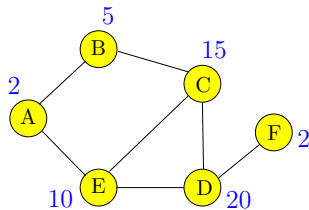
# Part I

## Maximum Weighted Independent Set in Trees

# Maximum Weight Independent Set Problem

**Input** Graph  $\mathbf{G} = (\mathbf{V}, \mathbf{E})$  and weights  $\mathbf{w}(\mathbf{v}) \geq 0$  for each  $\mathbf{v} \in \mathbf{V}$

**Goal** Find maximum weight independent set in  $\mathbf{G}$

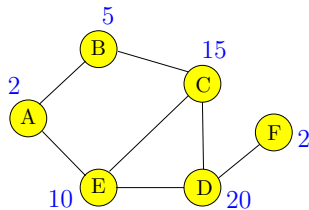


Maximum weight independent set in above graph:  $\{\mathbf{B}, \mathbf{D}\}$

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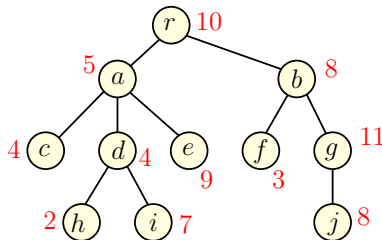


Maximum weight independent set in above graph:  $\{B, D\}$

# Maximum Weight Independent Set in a Tree

**Input** Tree  $\mathbf{T} = (\mathbf{V}, \mathbf{E})$  and weights  $\mathbf{w}(\mathbf{v}) \geq 0$  for each  $\mathbf{v} \in \mathbf{V}$

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Maximum weight independent set in above tree: ??

# Towards a Recursive Solution

For an arbitrary graph  $G$ :

- 1 Number vertices as  $v_1, v_2, \dots, v_n$
- 2 Find recursively optimum solutions without  $v_n$  (recurse on  $G - v_n$ ) and with  $v_n$  (recurse on  $G - v_n - N(v_n)$  & include  $v_n$ ).
- 3 Saw that if graph  $G$  is arbitrary there was no good ordering that resulted in a small number of subproblems.

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Natural candidate for  $v_n$  is root  $r$  of  $T$ ? Let  $\mathcal{O}$  be an optimum solution to the whole problem.

Case  $r \notin \mathcal{O}$  : Then  $\mathcal{O}$  contains an optimum solution for each subtree of  $T$  hanging at a child of  $r$ .

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# A Recursive Solution

**T(u)**: subtree of **T** hanging at node **u**

**OPT(u)**: max weighted independent set value in **T(u)**

$$\mathbf{OPT(u)} = \max \left\{ \sum_{v \text{ child of } u} \mathbf{OPT(v)}, \right. \\ \left. w(u) + \sum_{v \text{ grandchild of } u} \mathbf{OPT(v)} \right\}$$

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# Iterative Algorithm

- 1 Compute **OPT(u)** bottom up. To evaluate **OPT(u)** need to have computed values of all children and grandchildren of **u**
- 2 What is an ordering of nodes of a tree **T** to achieve above?  
Post-order traversal of a tree.

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# Iterative Algorithm

## MIS-Tree( $T$ ):

Let  $v_1, v_2, \dots, v_n$  be a post-order traversal of nodes of  $T$   
for  $i = 1$  to  $n$  do

$$M[v_i] = \max \left( \begin{array}{l} \sum_{v_j \text{ child of } v_i} M[v_j], \\ w(v_i) + \sum_{v_j \text{ grandchild of } v_i} M[v_j] \end{array} \right)$$

return  $M[v_n]$  (\* Note:  $v_n$  is the root of  $T$  \*)

Space:  $O(n)$  to store the value at each node of  $T$

Running time:

- 1 Naive bound:  $O(n^2)$  since each  $M[v_i]$  evaluation may take  $O(n)$  time and there are  $n$  evaluations.
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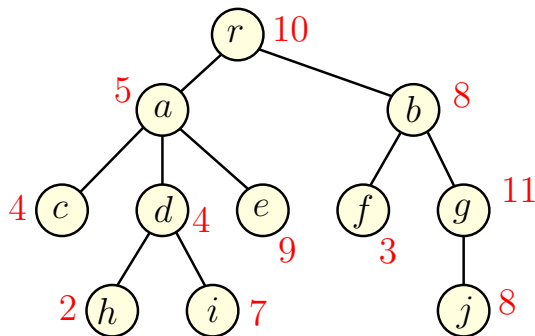
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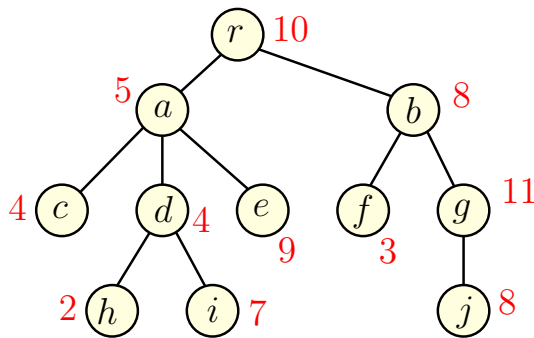
# Example



# Dominating set

## Definition

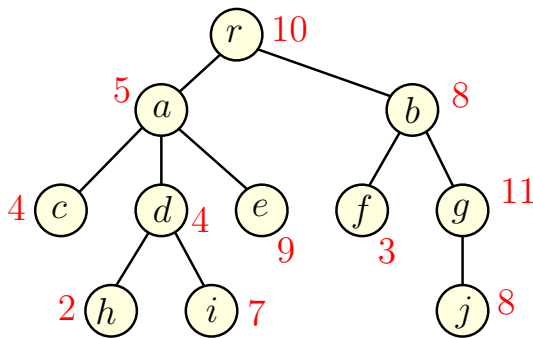
$G = (V, E)$ . The set  $X \subseteq V$  is a **dominating set**, if any vertex  $v \in V$  is either in  $X$  or is adjacent to a vertex in  $X$ .



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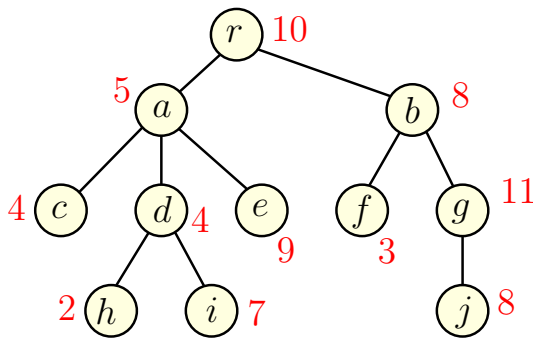
Given weights on vertices, compute the **minimum** weight dominating set in  $G$ .



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**Dominating Set** is **NP-Hard!**

## Part II

# DAGs and Dynamic Programming

# Recursion and DAGs

## Observation

Let **A** be a recursive algorithm for problem  $\Pi$ . For each instance **I** of  $\Pi$  there is an associated **DAG** **G(I)**.

- 1 Create directed graph **G(I)** as follows...
- 2 For each sub-problem in the execution of **A** on **I** create a node.
- 3 If sub-problem **v** depends on or recursively calls sub-problem **u** add directed edge **(u, v)** to graph.
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# Iterative Algorithm for...

## Dynamic Programming and DAGs

### Observation

*An iterative algorithm **B** obtained from a recursive algorithm **A** for a problem  $\Pi$  does the following:*

*For each instance **I** of  $\Pi$ , it computes a topological sort of **G(I)** and evaluates sub-problems according to the topological ordering.*

- 1 Sometimes the DAG **G(I)** can be obtained directly without thinking about the recursive algorithm **A**
- 2 In some cases (**not all**) the computation of an optimal solution reduces to a shortest/longest path in DAG **G(I)**
- 3 Topological sort based shortest/longest path computation is dynamic programming!

# A quick reminder...

## A Recursive Algorithm for weighted interval scheduling

Let  $O_i$  be value of an optimal schedule for the first  $i$  jobs.

```
Schedule( $n$ ):  
  if  $n = 0$  then return 0  
  if  $n = 1$  then return  $w(v_1)$   
   $O_{p(n)} \leftarrow$  Schedule( $p(n)$ )  
   $O_{n-1} \leftarrow$  Schedule( $n - 1$ )  
  if  $(O_{p(n)} + w(v_n) < O_{n-1})$  then  
     $O_n = O_{n-1}$   
  else  
     $O_n = O_{p(n)} + w(v_n)$   
  return  $O_n$ 
```

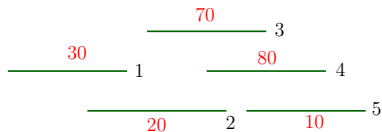
# Weighted Interval Scheduling via...

## Longest Path in a DAG

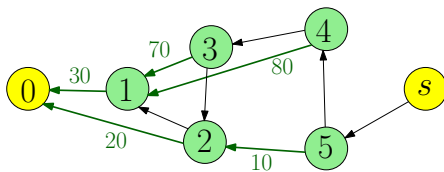
Given intervals, create a DAG as follows:

- 1 Create one node for each interval, plus a dummy sink node **0** for interval **0**, plus a dummy source node **s**.
- 2 For each interval **i** add edge **(i, p(i))** of the length/weight of **v<sub>i</sub>**.
- 3 Add an edge from **s** to **n** of length **0**.
- 4 For each interval **i** add edge **(i, i - 1)** of length **0**.

# Example



$$p(5) = 2, p(4) = 1, p(3) = 1, p(2) = 0, p(1) = 0$$





# Relating Optimum Solution

Given interval problem instance  $I$  let  $G(I)$  denote the DAG constructed as described.

## Claim

*Optimum solution to weighted interval scheduling instance  $I$  is given by longest path from  $s$  to  $t$  in  $G(I)$ .*

Assuming claim is true,

- 1 If  $I$  has  $n$  intervals, DAG  $G(I)$  has  $n + 2$  nodes and  $O(n)$  edges. Creating  $G(I)$  takes  $O(n \log n)$  time: to find  $p(i)$  for each  $i$ . How?
- 2 Longest path can be computed in  $O(n)$  time — recall  $O(m + n)$  algorithm for shortest/longest paths in DAGs.

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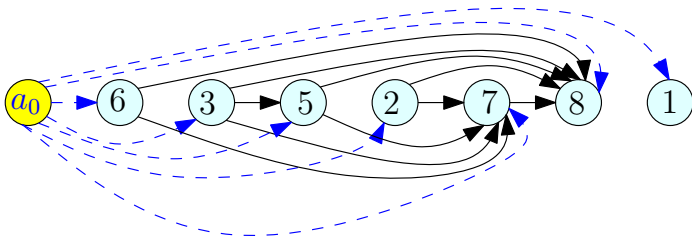
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# DAG for Longest Increasing Sequence

Given sequence  $a_1, a_2, \dots, a_n$  create DAG as follows:

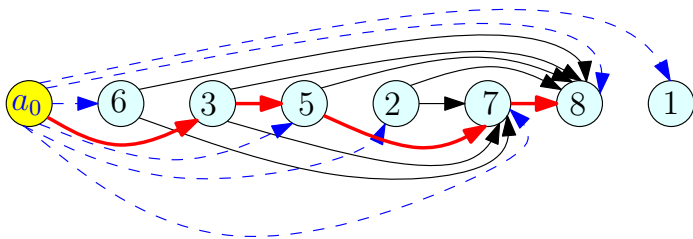
- 1 add sentinel  $a_0$  to sequence where  $a_0$  is less than smallest element in sequence
- 2 for each  $i$  there is a node  $v_i$
- 3 if  $i < j$  and  $a_i < a_j$  add an edge  $(v_i, v_j)$
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## Part III

# Edit Distance and Sequence Alignment

# Spell Checking Problem

Given a string “exponen” that is not in the dictionary, how should a spell checker suggest a *nearby* string?

What does nearness mean?

**Question:** Given two strings  $x_1x_2 \dots x_n$  and  $y_1y_2 \dots y_m$  what is a *distance* between them?

**Edit Distance:** minimum number of “edits” to transform  $x$  into  $y$ .

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# Edit Distance

## Definition

**Edit distance** between two words **X** and **Y** is the number of letter insertions, letter deletions and letter substitutions required to obtain **Y** from **X**.

## Example

The edit distance between FOOD and MONEY is at most **4**:

FOOD → MOOD → MONOD → MONED → MONEEY

# Edit Distance: Alternate View

## Alignment

Place words one on top of the other, with gaps in the first word indicating insertions, and gaps in the second word indicating deletions.

F	O	O		D
M	O	N	E	Y

Formally, an **alignment** is a set  $M$  of pairs  $(i, j)$  such that each index appears at most once, and there is no “crossing”:  $i < i'$  and  $i$  is matched to  $j$  implies  $i'$  is matched to  $j' > j$ . In the above example, this is  $M = \{(1, 1), (2, 2), (3, 3), (4, 5)\}$ . Cost of an alignment is the number of mismatched columns plus number of unmatched indices in both strings.

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# Edit Distance Problem

## Problem

Given two words, find the edit distance between them, i.e., an alignment of smallest cost.

# Applications

- 1 Spell-checkers and Dictionaries
- 2 Unix diff
- 3 DNA sequence alignment ... but, we need a new metric

# Similarity Metric

## Definition

For two strings **X** and **Y**, the cost of alignment **M** is

- ① [Gap penalty] For each gap in the alignment, we incur a cost  $\delta$ .
- ② [Mismatch cost] For each pair **p** and **q** that have been matched in **M**, we incur cost  $\alpha_{pq}$ ; typically  $\alpha_{pp} = 0$ .

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# An Example

## Example

o		c	u	r	r	a	n	c	e
o	c	c	u	r	r	e	n	c	e

$$\text{Cost} = \delta + \alpha_{ae}$$

Alternative:

o		c	u	r	r		a	n	c	e
o	c	c	u	r	r	e		n	c	e

$$\text{Cost} = 3\delta$$

Or a really stupid solution (delete string, insert other string):

o	c	u	r	r	a	n	c	e											
									o	c	c	u	r	r	e	n	c	e	

$$\text{Cost} = 19\delta.$$

# Sequence Alignment

**Input** Given two words  $\mathbf{X}$  and  $\mathbf{Y}$ , and gap penalty  $\delta$  and mismatch costs  $\alpha_{pq}$

**Goal** Find alignment of minimum cost

# Edit distance

## Basic observation

Let  $\mathbf{X} = \alpha\mathbf{x}$  and  $\mathbf{Y} = \beta\mathbf{y}$

$\alpha, \beta$ : strings.

$\mathbf{x}$  and  $\mathbf{y}$  single characters.

Think about optimal edit distance between  $\mathbf{X}$  and  $\mathbf{Y}$  as alignment, and consider last column of alignment of the two strings:

$\alpha$	$\mathbf{x}$
$\beta$	$\mathbf{y}$

or

$\alpha$	$\mathbf{x}$
$\beta\mathbf{y}$	

or

$\alpha\mathbf{x}$	
$\beta$	$\mathbf{y}$

## Observation

*Prefixes must have optimal alignment!*

# Problem Structure

## Observation

Let  $\mathbf{X} = x_1x_2 \cdots x_m$  and  $\mathbf{Y} = y_1y_2 \cdots y_n$ . If  $(m, n)$  are not matched then either the  $m$ th position of  $\mathbf{X}$  remains unmatched or the  $n$ th position of  $\mathbf{Y}$  remains unmatched.

- ① Case  $x_m$  and  $y_n$  are matched.
  - ① Pay mismatch cost  $\alpha_{x_my_n}$  plus cost of aligning strings  $x_1 \cdots x_{m-1}$  and  $y_1 \cdots y_{n-1}$
- ② Case  $x_m$  is unmatched.
  - ① Pay gap penalty plus cost of aligning  $x_1 \cdots x_{m-1}$  and  $y_1 \cdots y_n$
- ③ Case  $y_n$  is unmatched.
  - ① Pay gap penalty plus cost of aligning  $x_1 \cdots x_m$  and  $y_1 \cdots y_{n-1}$

# Subproblems and Recurrence

## Optimal Costs

Let  $\text{Opt}(i, j)$  be optimal cost of aligning  $x_1 \cdots x_i$  and  $y_1 \cdots y_j$ . Then

$$\text{Opt}(i, j) = \min \begin{cases} \alpha_{x_i y_j} + \text{Opt}(i - 1, j - 1), \\ \delta + \text{Opt}(i - 1, j), \\ \delta + \text{Opt}(i, j - 1) \end{cases}$$

Base Cases:  $\text{Opt}(i, 0) = \delta \cdot i$  and  $\text{Opt}(0, j) = \delta \cdot j$

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# Dynamic Programming Solution

```
for all  $i$  do  $M[i, 0] = i\delta$ 
for all  $j$  do  $M[0, j] = j\delta$ 

for  $i = 1$  to  $m$  do
  for  $j = 1$  to  $n$  do
     $M[i, j] = \min \begin{cases} \alpha_{x_i y_j} + M[i - 1, j - 1], \\ \delta + M[i - 1, j], \\ \delta + M[i, j - 1] \end{cases}$ 
```

## Analysis

- 1 Running time is  $O(mn)$ .

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# Dynamic Programming Solution

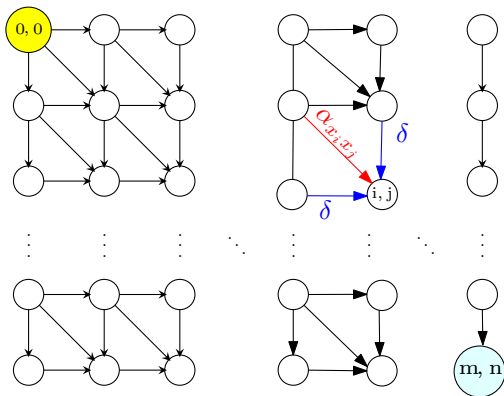
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```

## Analysis

- 1 Running time is  $O(mn)$ .
- 2 Space used is  $O(mn)$ .

# Matrix and DAG of Computation



**Figure:** Iterative algorithm in previous slide computes values in row order. Optimal value is a shortest path from  $(0,0)$  to  $(m,n)$  in .

# Sequence Alignment in Practice

- 1 Typically the DNA sequences that are aligned are about  $10^5$  letters long!
- 2 So about  $10^{10}$  operations and  $10^{10}$  bytes needed
- 3 The killer is the 10GB storage
- 4 Can we reduce space requirements?

# Optimizing Space

## 1 Recall

$$M(i, j) = \min \begin{cases} \alpha_{x_i y_j} + M(i - 1, j - 1), \\ \delta + M(i - 1, j), \\ \delta + M(i, j - 1) \end{cases}$$

- 2 Entries in **j**th column only depend on **(j - 1)**st column and earlier entries in **j**th column
- 3 Only store the current column and the previous column reusing space; **N(i, 0)** stores **M(i, j - 1)** and **N(i, 1)** stores **M(i, j)**

# Computing in column order to save space

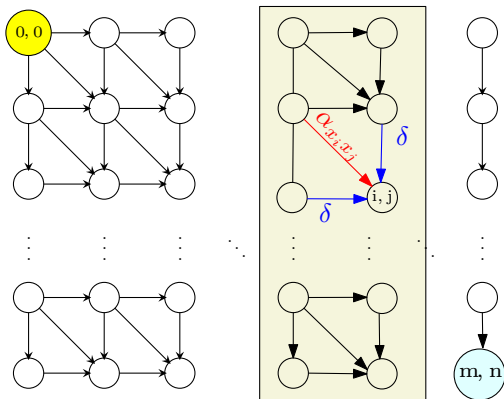


Figure:  $M(i, j)$  only depends on previous column values. Keep only two columns and compute in column order.

# Space Efficient Algorithm

```
for all i do  $N[i, 0] = i\delta$ 
for j = 1 to n do
   $N[0, j] = j\delta$  (* corresponds to  $M(0, j)$  *)
  for i = 1 to m do
    
$$N[i, 1] = \min \begin{cases} \alpha_{x_i y_j} + N[i - 1, 0] \\ \delta + N[i - 1, 1] \\ \delta + N[i, 0] \end{cases}$$

  for i = 1 to m do
    Copy  $N[i, 0] = N[i, 1]$ 
```

## Analysis

Running time is  $O(mn)$  and space used is  $O(2m) = O(m)$

# Analyzing Space Efficiency

- 1 From the  $m \times n$  matrix  $M$  we can construct the actual alignment (exercise)
- 2 Matrix  $N$  computes cost of optimal alignment but no way to construct the actual alignment
- 3 Space efficient computation of alignment? More complicated algorithm — see text book.

# Takeaway Points

- 1 Dynamic programming is based on finding a recursive way to solve the problem. Need a recursion that generates a small number of subproblems.
- 2 Given a recursive algorithm there is a natural **DAG** associated with the subproblems that are generated for given instance; this is the dependency graph. An iterative algorithm simply evaluates the subproblems in some topological sort of this **DAG**.
- 3 The space required to evaluate the answer can be reduced in some cases by a careful examination of that dependency **DAG** of the subproblems and keeping only a subset of the **DAG** at any time.





# Notes



# Notes