

Interactive Computer Graphics



CS 418 – Spring 2011

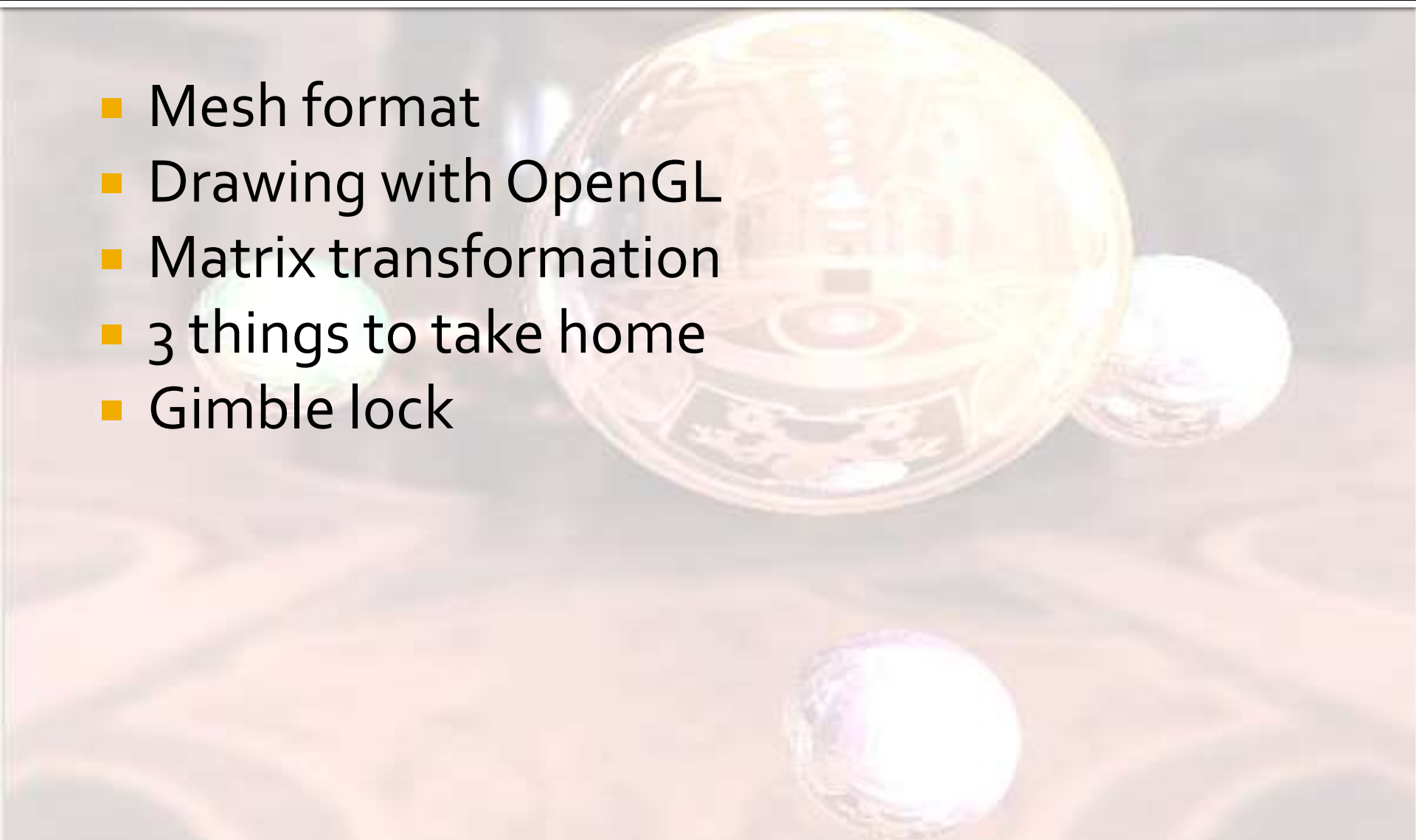
Mesh Rendering, Transformation,
Camera Viewing and Projection
in OpenGL

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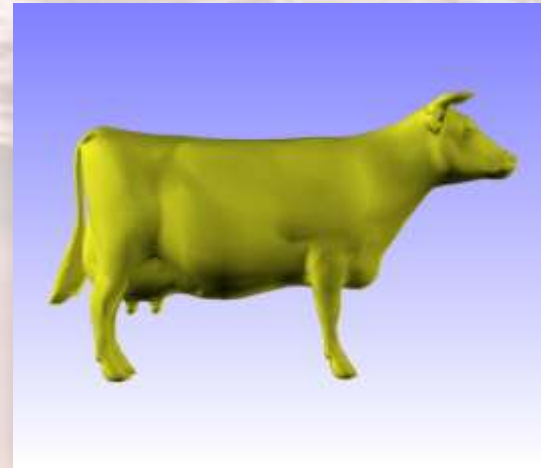
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Agenda

- Mesh format
 - Drawing with OpenGL
 - Matrix transformation
 - 3 things to take home
 - Gimble lock
- 

How to Load Your Mesh

- Customized .obj 3D models **with colors**.
- Won't work with a obj reader code.
- You should have skills to write a simple parser loading the files.



Our Mesh File Format

Position v1 v 0.0 0.0 0.0

Position v2 v 1.0 0.0 0.0

.....

Color v1 vc 1 0 0

Color v2 vc 0 0 1

.....

f 1 2 3

f 1 3 4

.....

- You will have a list of vertex attributes : Positions (v), Colors (vc), etc.
- Vertices are indexed according to their orders in file.
- Another indexed list for triangles (f)
 - Ex : Triangle 1 is formed by vertex v1,v2 and v3

Exercise

Draw the object from the given vertex/face list :

V 0.0 0.0 0.0

V 1.0 0.0 0.0

V 1.0 1.0 0.0

V 0.0 1.0 0.0

VC 1 0 0

VC 0 0 1

VC 1 0 0

VC 0 1 0

f 1 2 3

f 1 3 4

Mesh Structure

- Face-index List :
 - Recommend to use/implement basic matrix/vector structure and operations. (ex : **libgfx**)
 - Store vertex attributes in one array
 - Store face-vertex indices in another array.
 - When rendering, iterate through each face, and grab vertex attributes based on Indices.
 - More complicated structure is possible → Half-Edge, etc.

Display Your Mesh

- Assuming you've set up the view/projection transformation.
- Display one triangle

```
glBegin(GL_TRIANGLES);  
    glVertex3f(x1,y1,z1);  
    glVertex3f(x2,y2,z2);  
    glVertex3f(x3,y3,z3);  
glEnd();
```
- glBegin → Decide which primitive you will display.
 - GL_POINTS, GL_LINES, GL_TRIANGLES, etc.
- Display a mesh is similar, just go through each triangle in the mesh.
(Put loop between glBegin/glEnd)

Color Your Mesh

- glColor3f → Set R,G,B color
 - Range from 0.0~1.0. (1.0,1.0,1.0) is white.
- Use the provided colors, or generate your own.
- Ex : Color one triangle with Red, Green, Blue at each vertex

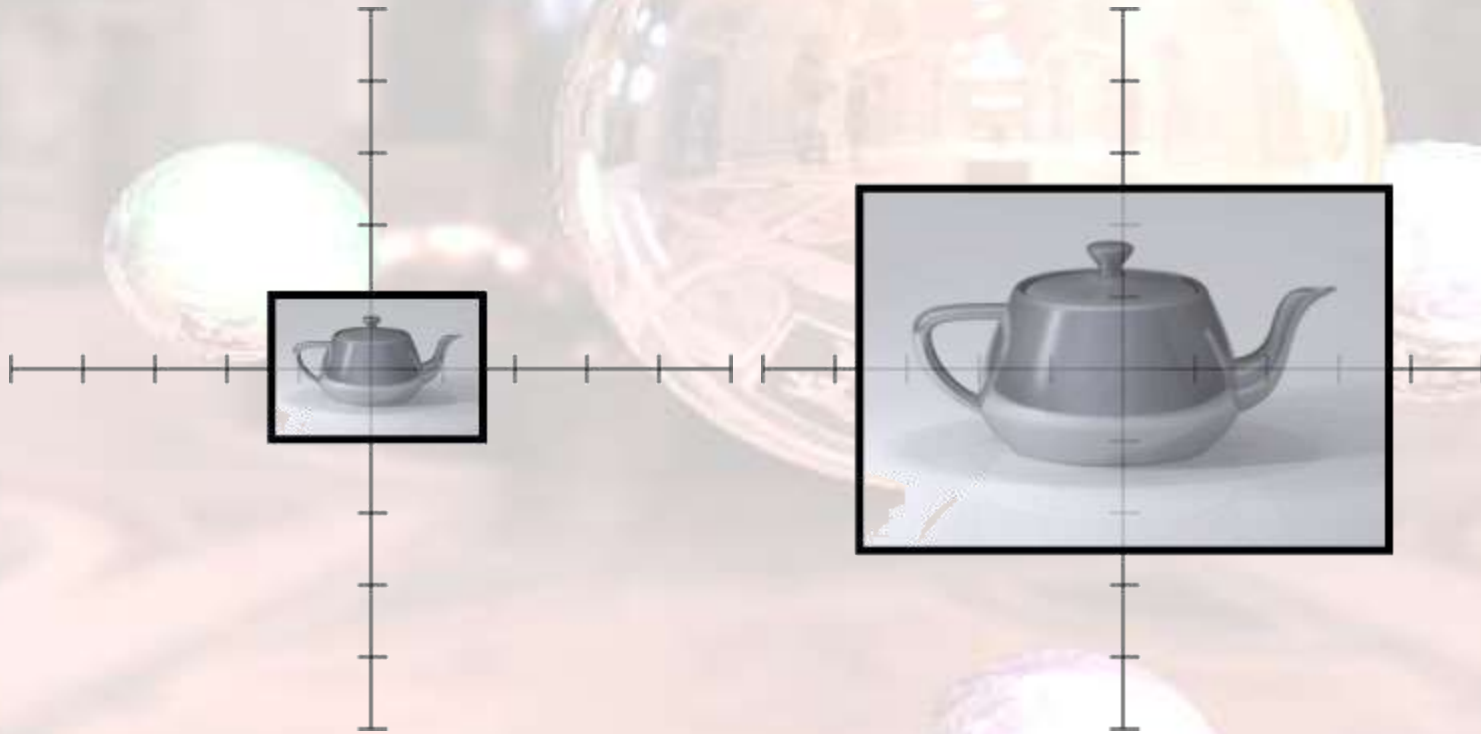
```
glBegin(GL_TRIANGLES);  
    glColor3f(1.0,0.0,0.0); //red  
    glVertex3f(x1,y1,z1);  
    glColor3f(0.0,1.0,0.0); // green  
    glVertex3f(x2,y2,z2);  
    glColor3f(0.0,0.0,1.0); // blue  
    glVertex3f(x3,y3,z3);  
glEnd();
```


OpenGL Matrix Transformation

- Essential for interactive viewing/animation.
- Things to Take Home
 - #1 : You are modifying a global “current matrix”
 - #2 : The “last” transformation gets applied “first”.
 - #3 : OpenGL store matrix in “Column Major”

Review of Matrix Ops.

- `glScalef (2.5, 2.5, 1.0);`



Scaling

$$\begin{bmatrix} a & & & \\ & b & & \\ & & c & \\ & & & 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} ax \\ by \\ cz \\ 1 \end{bmatrix}$$

Translation

- `glTranslatef(2.5, 2.0, 0.0);`

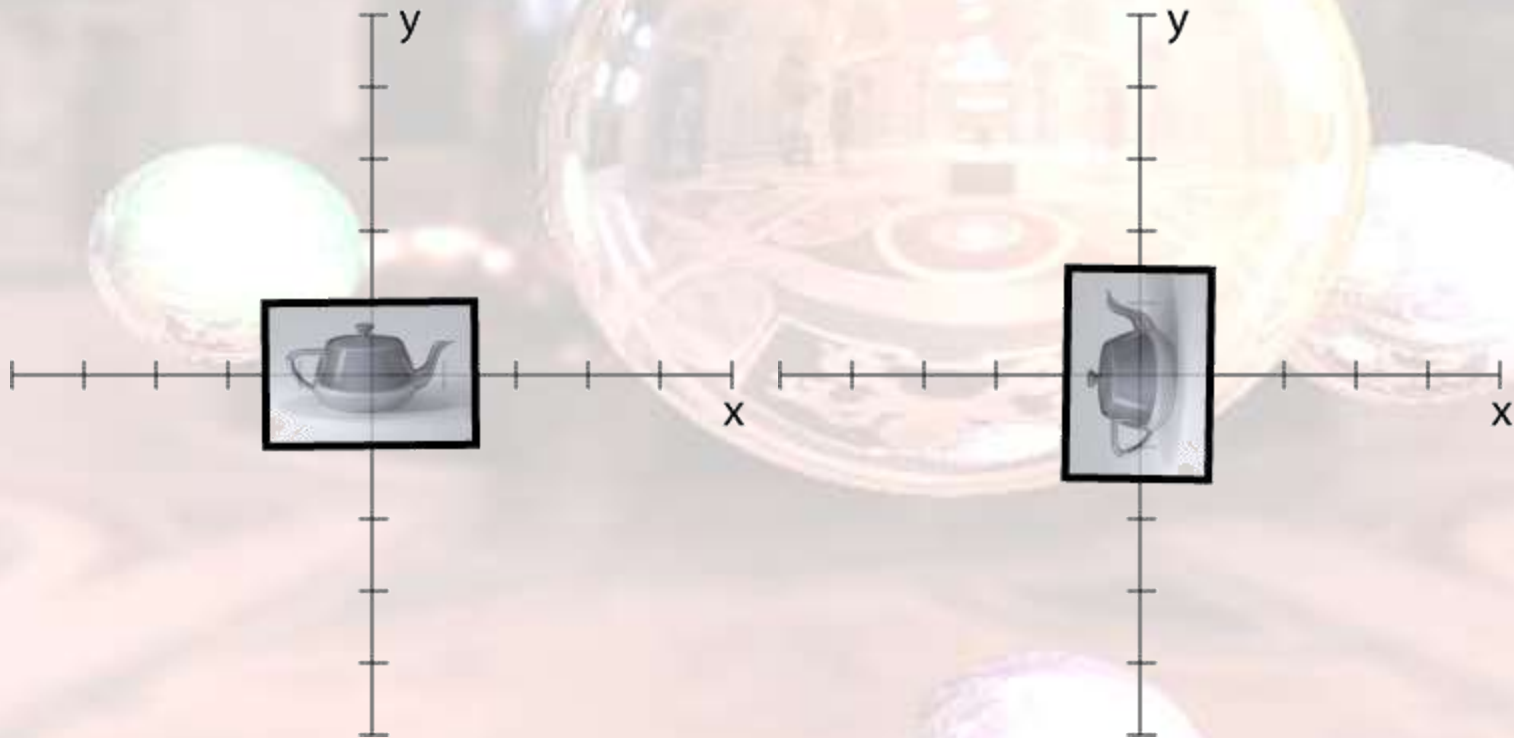


Translation

$$\begin{bmatrix} 1 & & & & \\ & 1 & & & \\ & & 1 & & \\ & & & 1 & \\ & & & & 1 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ 1 \end{bmatrix} \begin{bmatrix} x \\ y \\ z \\ 1 \end{bmatrix} = \begin{bmatrix} x+a \\ y+b \\ z+c \\ 1 \end{bmatrix}$$

Rotation

- `glRotatef(90.0, 0.0, 0.0, 1.0)`



Rotation

- About x -axis
– rotates $y \rightarrow z$

- About y -axis
– rotates $z \rightarrow x$

- About z -axis
– rotates $x \rightarrow y$

$$\begin{bmatrix} 1 & & & & & \\ & \cos \theta & -\sin \theta & & & \\ & \sin \theta & \cos \theta & & & \\ & & & 1 & & \\ & & & & \cos \theta & -\sin \theta \\ & & & & \sin \theta & \cos \theta \\ & & & & & & 1 \\ & & & & & & & 1 \end{bmatrix}$$

- You may also specify rotation about an arbitrary axis.

#1 Current Matrix

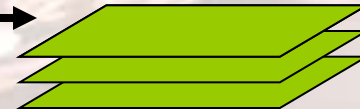
- An OpenGL matrix operation affects a **global 4x4 matrix**.
- It is the top matrix in the matrix stack you are currently working on. → **glMatrixMode**

```
glMatrixMode(GL_MODEL_VIEW)  
glRotatef(1.0,0.0,0.0,1.0);
```

Current Matrix



Model View Matrix



$M1 = M1 * R$

```
glMatrixMode(GL_PROJECTION)  
gluPerspective(...);
```

Projection Matrix



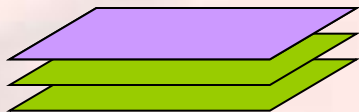
$M2 = M2 * P$

#1 Current Matrix

- When rendering, both of them are combined to transform the object.



Model View Matrix



$$\text{MVP} = (\text{Projection}) * (\text{Model View})$$

$$\text{V_Transform} = \text{MVP} * \text{V}$$

#2 Last Transform Applied First

- OpenGL Post-multiply new transformation with current matrix when we call `glRotate`, `glTranslate`, or `glScale`.

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} \times \begin{bmatrix} 0.5 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 0.5 & 0 & 0 & 0 \\ 0 & 0.5 & 0 & 0 \\ 0 & 0 & 0.5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} \text{Current} \\ \text{ModelView} \\ \text{Matrix} \end{bmatrix} \times \begin{bmatrix} \text{glScale} \\ \text{Matrix} \end{bmatrix} = \begin{bmatrix} \text{New} \\ \text{ModelView} \\ \text{Matrix} \end{bmatrix}$$

- The last transformation is applied first to the object.

```
glLoadIdentity();
```

```
glRotatef(1.0,0.0,0.0,1.0);
```

```
glTranslatef(0.5,0.5,0.5);
```

M=IRT

```
glLoadIdentity();
```

```
glTranslatef(0.5,0.5,0.5);
```

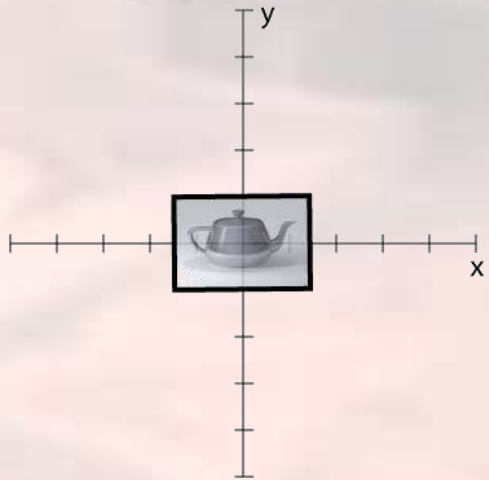
```
glRotatef(1.0,0.0,0.0,1.0);
```

M=ITR

Exercise

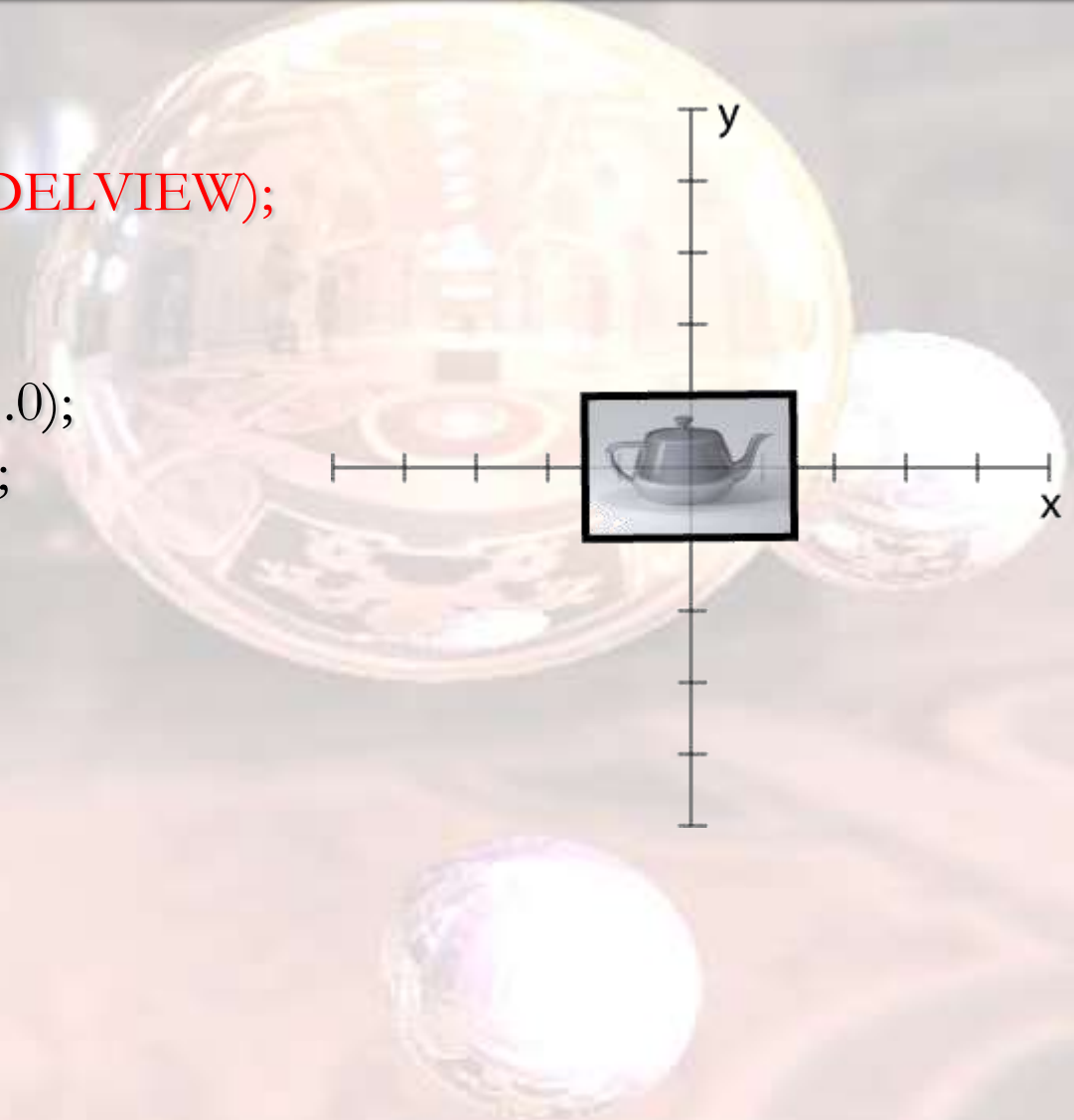
Draw the result of the following OpenGL transformation code.

```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
glScalef(1.5, 1.0, 1.0);  
glRotatef(90.0, 0.0, 0.0, 1.0);  
glTranslatef(2.0, 2.0, 0.0);  
draw_teapot_image();
```



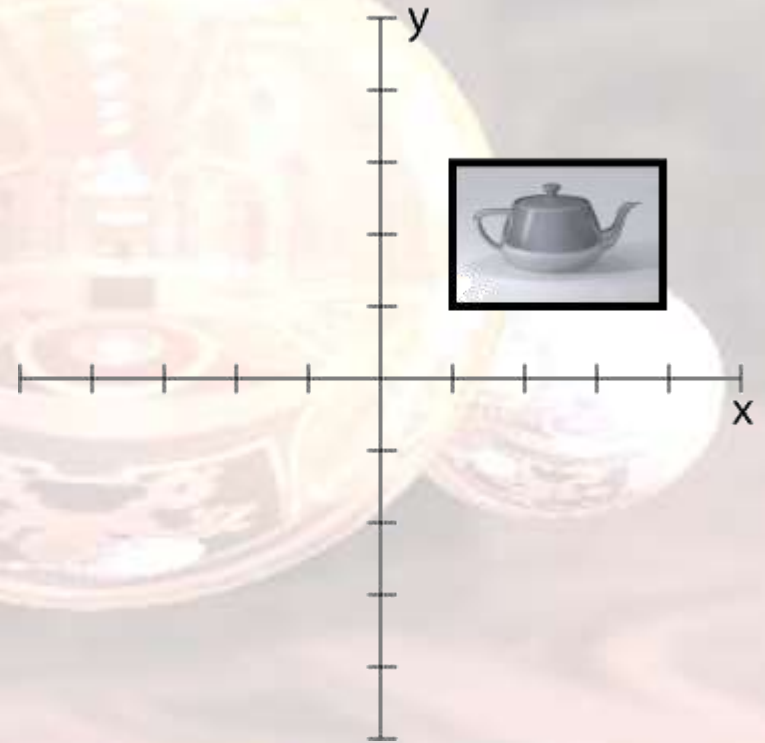
Exercise

```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
glScalef(1.5, 1.0, 1.0);  
glRotatef(90.0, 0.0, 0.0, 1.0);  
glTranslatef(2.0, 2.0, 0.0);  
draw_teapot_image();
```



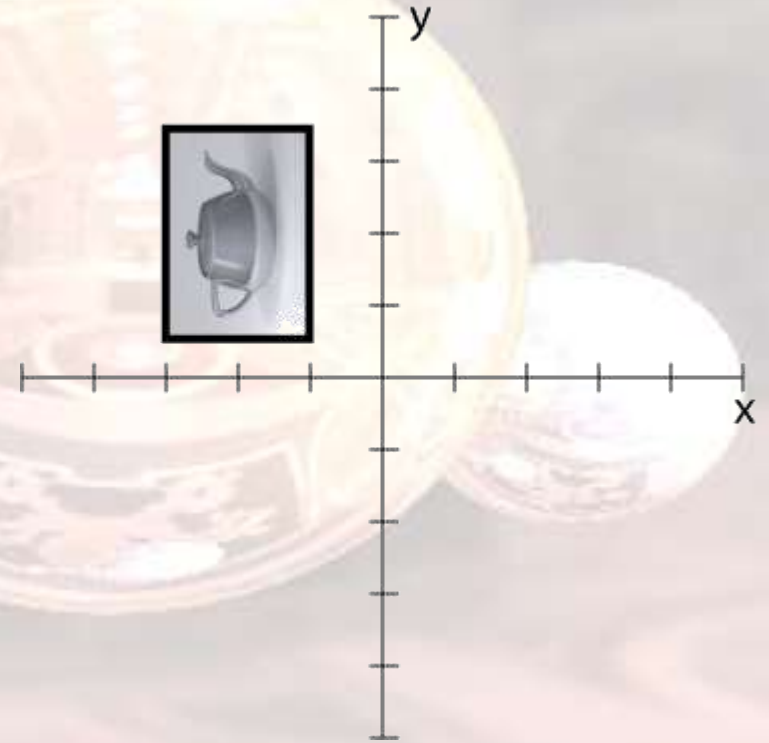
Exercise

```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
glScalef(1.5, 1.0, 1.0);  
glRotatef(90.0, 0.0, 0.0, 1.0);  
glTranslatef(2.0, 2.0, 0.0);  
draw_teapot_image();
```



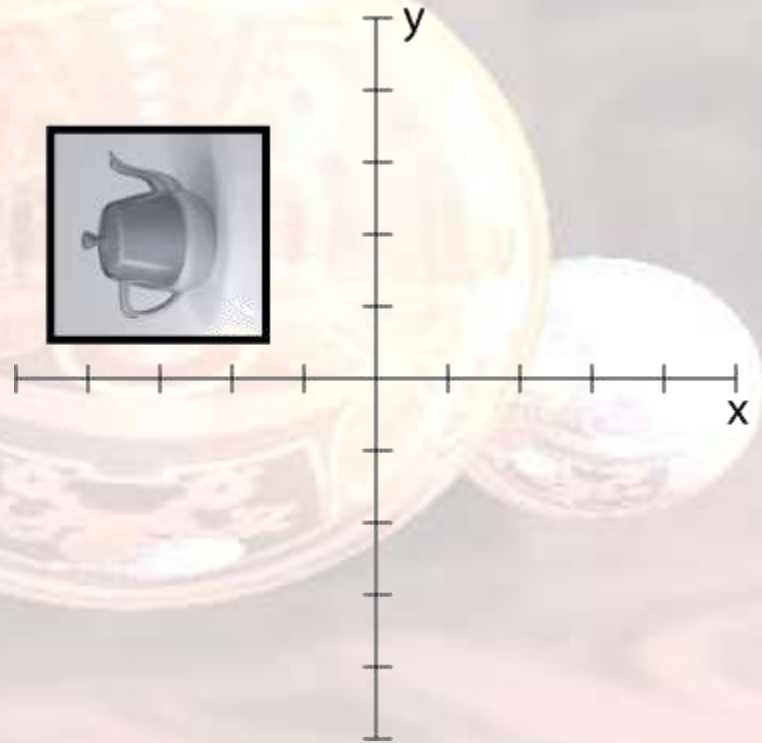
Exercise

```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
glScalef(1.5, 1.0, 1.0);  
glRotatef(90.0, 0.0, 0.0, 1.0);  
glTranslatef(2.0, 2.0, 0.0);  
draw_teapot_image();
```



Exercise

```
glMatrixMode(GL_MODELVIEW);  
glLoadIdentity();  
glScalef(1.5, 1.0, 1.0);  
glRotatef(90.0, 0.0, 0.0, 1.0);  
glTranslatef(2.0, 2.0, 0.0);  
draw_teapot_image();
```



Useful OpenGL Matrix Ops.

- `glLoadIdentity` : $M = I$
- `glScale` : $M = MS$
- `glTranslate` : $M = MT$
- `glRotate` : Specify rotation axis, angle. $M = MR$

Useful OpenGL Matrix Ops.

- `glLoadMatrix(Mo)` : $M = Mo$
- `glGetFloat(MatrixMode, Mo)` : $Mo = M$
- `glMultMatrix(Mo)` : $M = M * Mo$
- Caveat : OpenGL store matrix in "**Column Major**" instead of "**Row Major**"

Column Major

Given a 1D array of 16 floats :

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
---	---	---	---	---	---	---	---	---	----	----	----	----	----	----	----

2D array in C :

1	2	3	4
5	6	7	8
9	10	11	12
13	14	15	16

Matrix in OpenGL :

1	5	9	13
2	6	10	14
3	7	11	15
4	8	12	16

Pre-multiply ?

- What to do if you want to pre-multiply the matrix ?

$M=RM$?

- Make use of “glGetFloat” & “glMultMatrix”.

```
glLoadIdentity();
```

```
glTranslatef(0.3,0.3,0.2);
```

```
glGetFloat(MODEL_VIEW,tempM);
```

```
glLoadIdentity();
```

```
glRotatef(1.0,0.0,0.0,1.0);
```

```
glMultMatrix(tempM);
```

$tempM=M=IT$

$M=IRtempM$

- Useful for updating transformation with UI control.

MP₁ : Mesh Rendering

- Due on Sep. 25, 2012 at 3:30pm
 - Compass is sometimes not very stable. Try to submit earlier.
 - Email me if you encounter last minute failure on Compass.
- Depth Test : **`glEnable(GL_DEPTH_TEST);`**
- `glRotate3f` :
 - OpenGL will normalize the axis.

Interactive Viewing

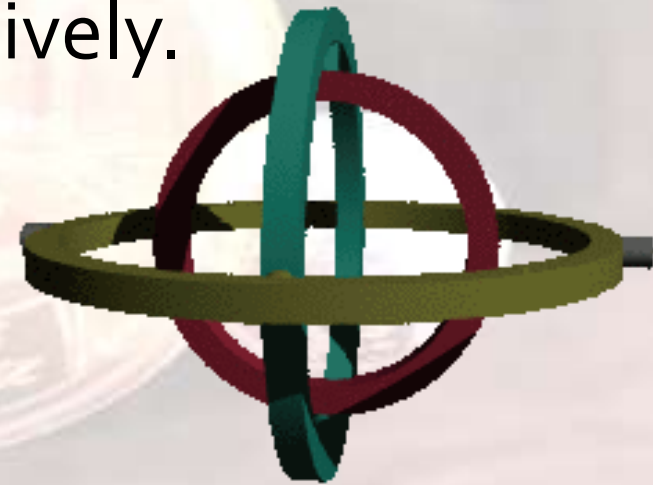
- Interactive viewing is desired for 3D model display.
- Adjust the orientation of shape with UI
 - FPS style : Changing the first person view
 - Exploring the environment
 - ArcBall (TrackBall) : Rotate the object at view center.
 - Easier to view a single object in all direction

Euler Angles

- At most 75% of credit if you only implement Euler Angles.
- Rotate about X,Y,Z axis respectively.
- Very easy to implement.
- Keep track of X,Y,Z angles.

```
glRotatef(angleX,1,0,0);  
glRotatef(angleY,0,1,0);  
glRotatef(angleZ,0,0,1);  
drawObject();
```

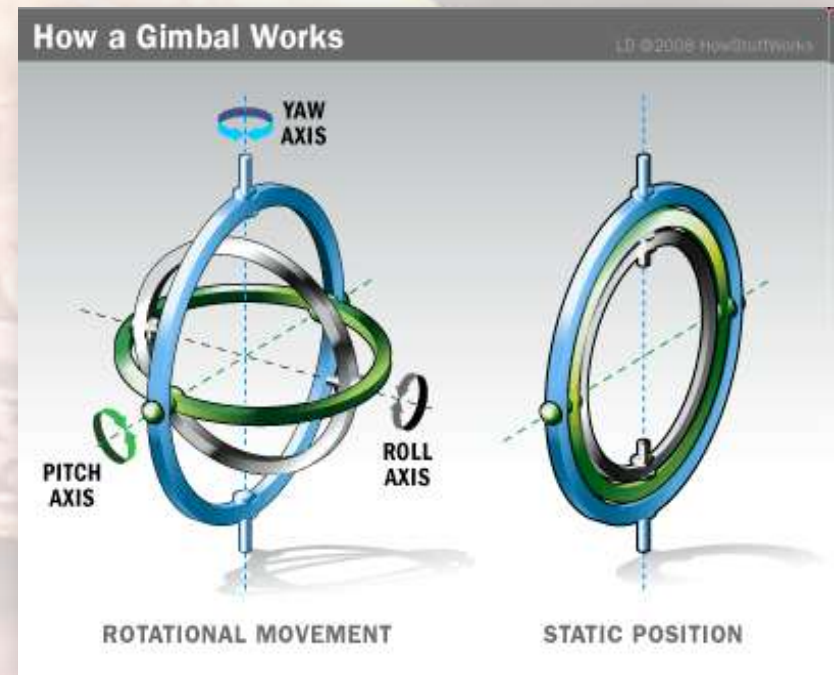
```
gluUnProject(mouse_x, mouse_y, 0.0, modelview_matrix,  
             projection_matrix, viewport_matrix, &x, &y, &z)
```



Gyroscope
(From Wikipedia)

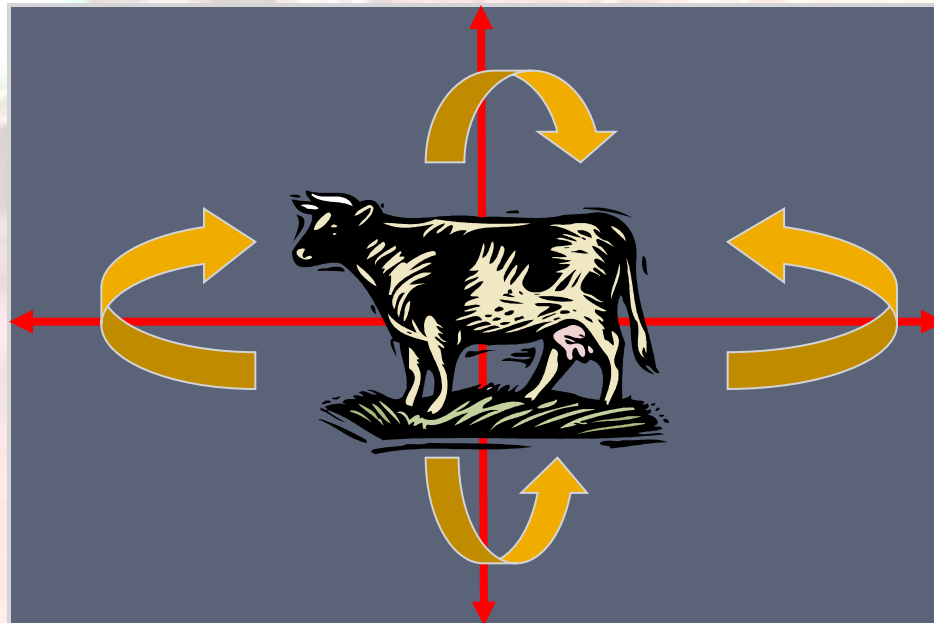
Euler Angles

- Problem : Gimbal Lock
- Occurs when two axes are aligned
- Second and third rotations have effect of transforming earlier rotations
 - ex: Rot x, Rot y, Rot z
 - If Rot y = 90 degrees, Rot z == -Rot x



Arcball Interface

- Intuition : Make use of the mouse position to control object orientation
 - Rotate object about some axis based on mouse movement



Arcball Interface

- Keep track a global rotation matrix R_g .
- Whenever there is a mouse movement, create a new rotation R_n .
- Update global rotation matrix $R_g = R_n * R_g$.
- How to define R_n ?

Arcball Interface

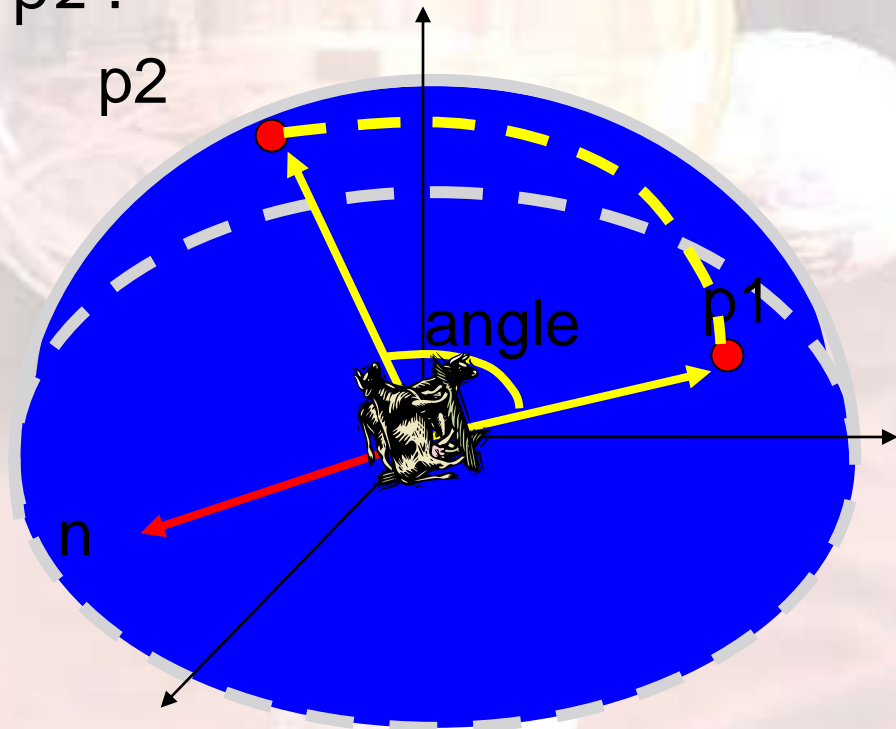
- To define a rotation : axis & angle
- Think of orientation as a point on the unit hemisphere
- How to rotate p_1 to p_2 ?

$$n = p_1 \times p_2$$

$$\text{axis} = n/|n|$$

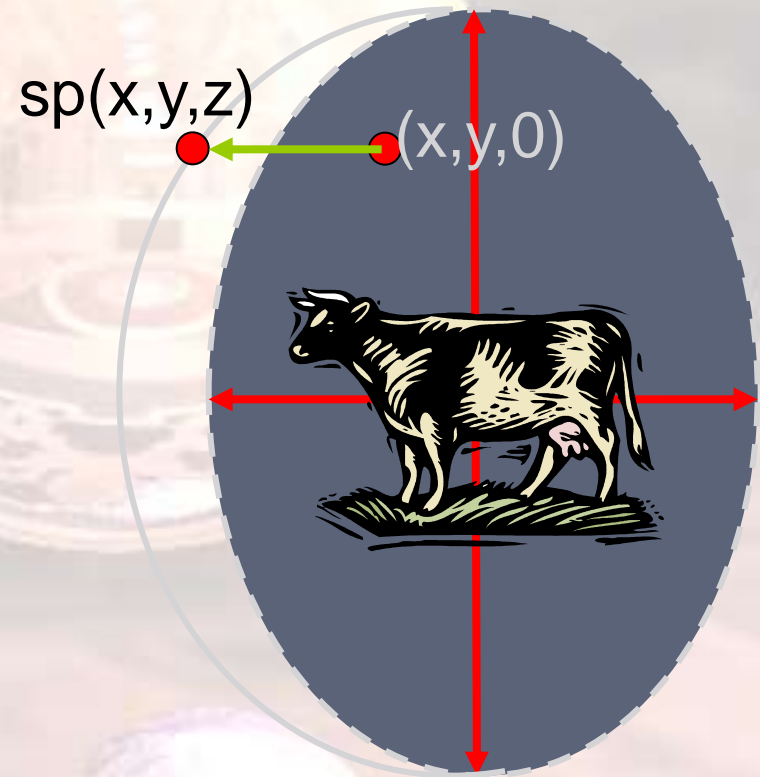
$$|n| = \sin(\text{angle})$$

$$\text{angle} = \text{asin}(|n|)$$



Arcball Interface

- How to find a point on sphere based on normalized screen coordinates ?
- Map a 2D point (x,y) back to a unit sphere
 - $z = \sqrt{1 - x*x - y*y}$



Arcball Interface

- Summary:
 - Get start/end mouse 2D position (glutMotion)
 - Map them to 3D points v_1, v_2 on hemi-sphere
 - Find rotation axis/angles from v_1, v_2
- Update object orientation with rotation axis/angle
 - (Pre-multiply new rotation with current rotation)

Rotation About Any Axis

- Check lecture note :

Let's suppose we have a unit direction vector

$$\mathbf{u} = \begin{bmatrix} x \\ y \\ z \end{bmatrix} \text{ where } x^2 + y^2 + z^2 = 1$$

We can derive a rotation by a given angle about this axis

$$\mathbf{R}(\theta, \mathbf{u}) = \mathbf{u}\mathbf{u}^T + \cos\theta(\mathbf{I} - \mathbf{u}\mathbf{u}^T) + (\sin\theta)\mathbf{u}^*$$

- You can also call `glRotate3f` to generate it.

Rendering Acceleration

- Calling glBegin/glEnd is not optimal.
 - Many function calls
 - Repeated vertices
 - Data transfer
- Acceleration :
 - Method 1: Display List
 - Method 2: VertexArray
 - Method 3: Vertex Buffer Object (VBO)



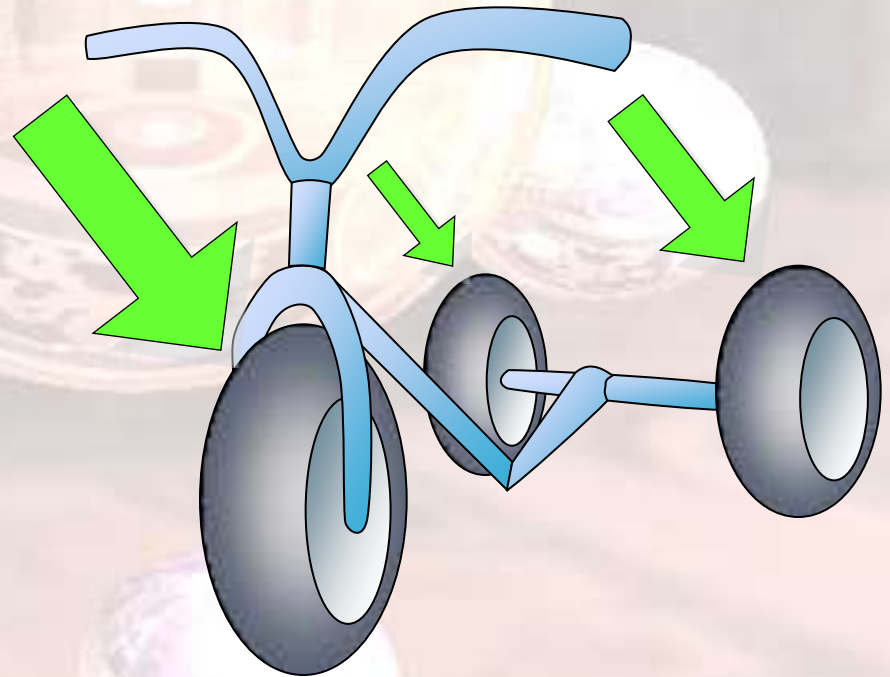
Display Lists

Method One

Display Lists


A display list is a convenient and efficient way to name and organize a set of OpenGL commands.

```
glCallList( wheel_id );  
modelview transformation  
glCallList( wheel_id );  
modelview transformation  
glCallList( wheel_id );
```



Display Lists

To optimize performance, an OpenGL display list is a cache of commands rather than a dynamic database.



In other words, once a display list is created, it can't be modified on the fly.

Display List

- A Display List is simply a group of OpenGL commands and arguments
- Most OpenGL drivers compile and accelerate Display Lists by
 - storing all static data on video ram
 - optimizing OpenGL commands execution
 - Frustum & occlusion culling
- Small driver overhead
- No time expensive data transfer

Display List

- Usage : Create a new list
 - Call glBegin/glEnd /glVertex to store commands in the display list.
 - glCallList to reuse a display list.

glGenList

glNewList

glEndList

glCallList

.....

Red Book Sixth Edition :
Chapter 7.

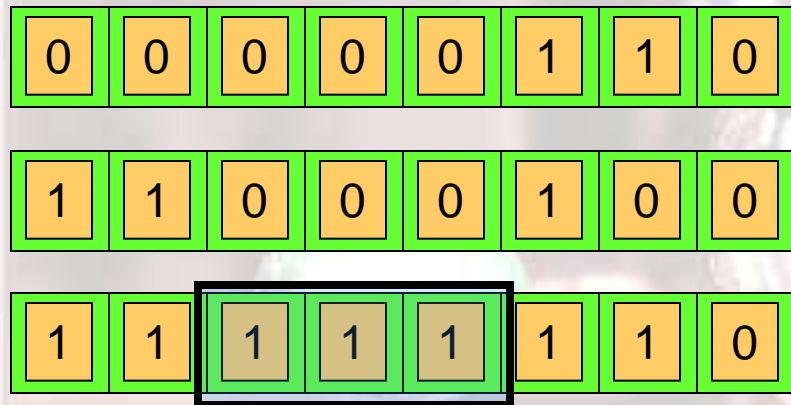
A 3D rendered scene featuring a large, highly reflective, golden-brown sphere in the center. It is surrounded by four smaller, similarly reflective spheres: one green on the left, one purple on the right, and two purple ones on the floor. The floor is highly reflective, showing clear reflections of the spheres. The background is a dark, blurred interior space with some architectural details.

Vertex Arrays

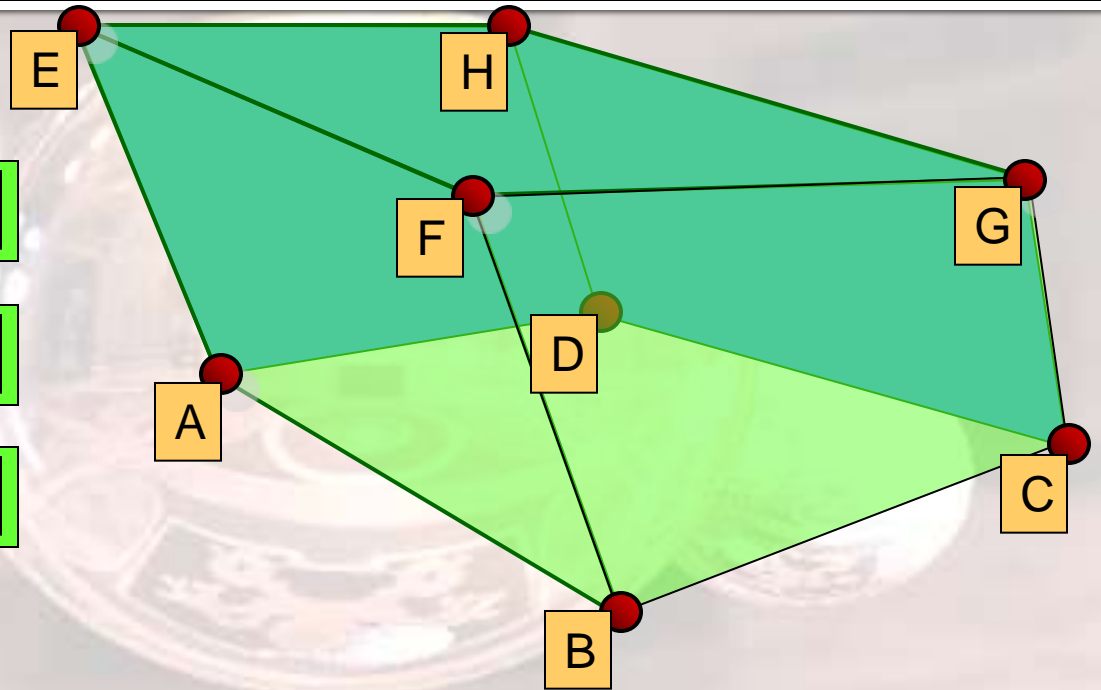
Method Two

The Basic Idea

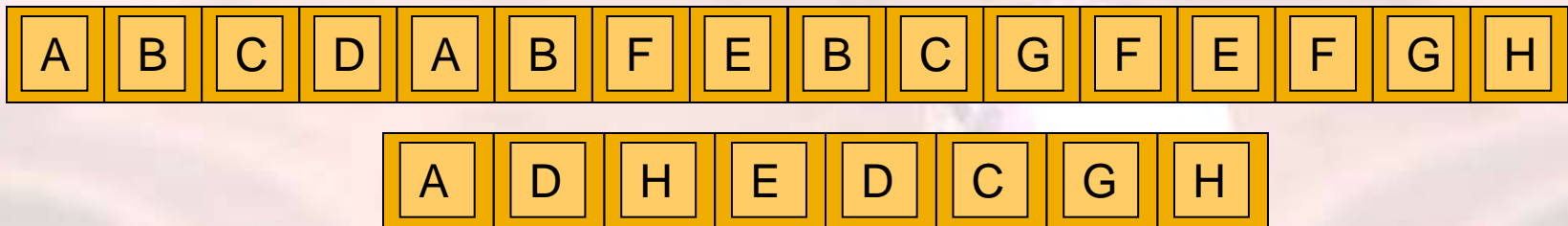
Vertices Stored in an Array



Vertex G



Indices of Quads into the vertex array



Vertex Arrays

- **Similar to conventional approach, but: One driver call for all vertices**
 - small driver overhead
- **Data resides in CPU memory.**
 - Easier to update
- **Still transferring all vertices**
 - lot of transfer (CPU/AGP-bound bottleneck)

Vertex Arrays

- Usage : Enable client state for vertex array.
 - Provide pointers to your vertices/faces in memory.
 - Call `glDrawElement` to rendering everything at once.

`glEnableClientState`

`glVertexPointer`

`glColorPointer`

`glDrawElements`

.....

Refer to Red Book for more information

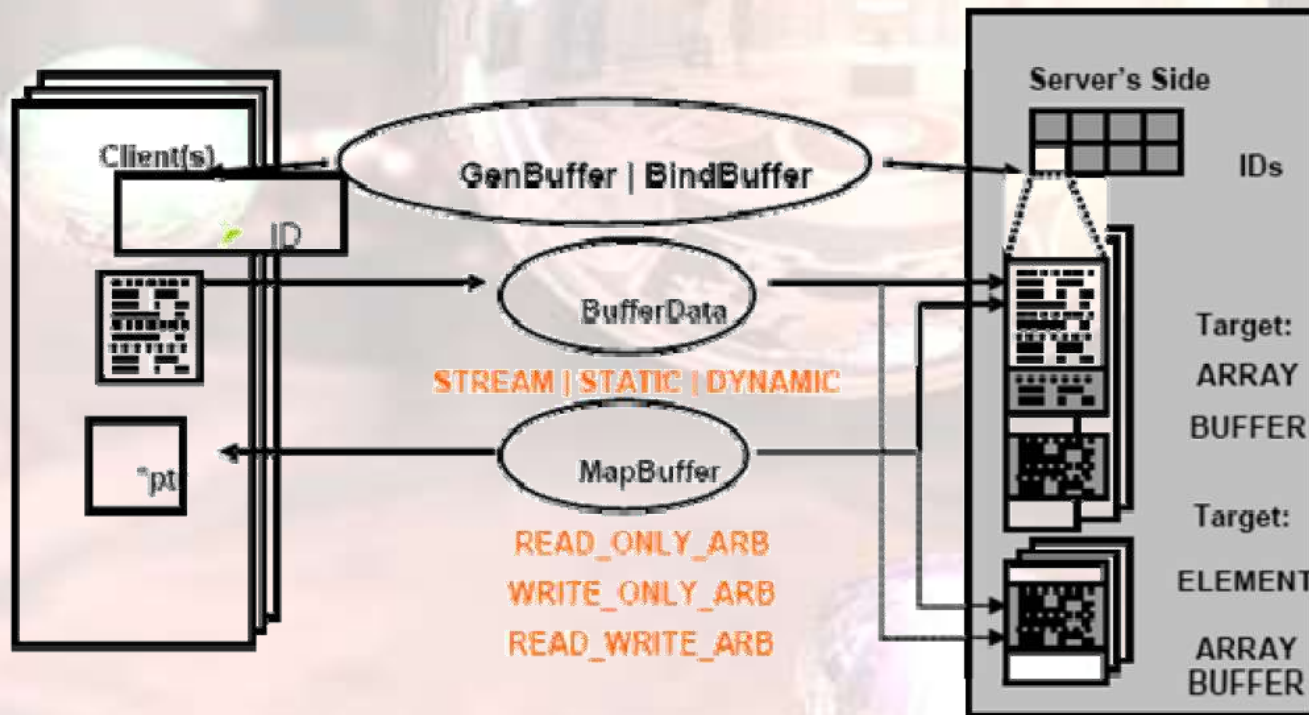


Buffer Object

Method Three

Vertex Buffer Object (VBO)

- A vertex buffer object (VBO) is a powerful feature that allows storing vertex data in video ram



Vertex Buffer Object (VBO)

- Very similar to vertex arrays
- VBOs hold geometry and state on the graphics hardware
 - Significant reduction in rendering time
- Provide mapping from application memory to graphics memory
 - Allows fast updates when geometry changes

Vertex Buffer Object

- Usage : Allocate enough buffer space in video memory.
 - Maps buffer memory to represent vertex/indices data.
 - Render as vertex arrays.

`glGenBuffers`

`glBindBuffers`

`glBufferData`

.....

Refer to the Red Book for
more details

Summary

- Use Display Lists or Vertex Buffer Objects to store **static objects**
- Vertex Arrays or dynamic Vertex Buffer for **deformable objects**
- DrawElements is expensive
 - draw as many Triangles per DrawElements as possible
- Keep data transfer as small as possible

Q&A

