Synchronization

CS 241

```
int X = 0; /**< Global variable used for counting. */</pre>
```

```
/**
 * Increments global variable X by 1 a total of TOTAL times.
 */
void* count up( void *ptr )
{
       int i = 0;
       for (i=0; i < TOTAL; i++)
             X++;
       return NULL;
}
void main()
{
       pthread t tid[2]; int i;
       for (i=0; i<2; i++) {</pre>
              pthread create(&tid[i], NULL, count up, NULL); }
       for (i=0; i<2; i++) {</pre>
              pthread join(tid[i], NULL); }
       printf("%d\n", X);
}
```

Assembly Code

C code for counter loop for thread i

for (i=0; i < 50000; i++)
 cnt++;</pre>

Corresponding assembly code

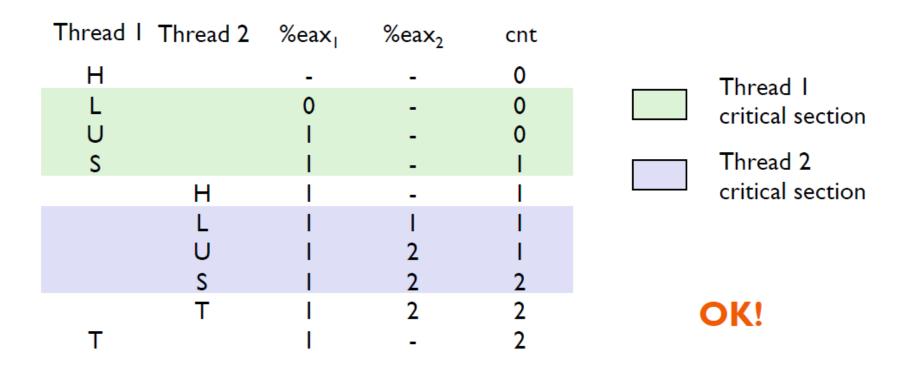
```
movl (%rdi),%ecx
       movl $0,%edx
                                       Head (H_i)
       cmpl %ecx,%edx
        jge .L13
.L11:
                                       Load cnt(L_i)
       movl cnt(%rip),%eax
                                       Update cnt(U_i)
        incl %eax
                                       Store cnt (S<sub>i</sub>)
       movl %eax,cnt(%rip)
       incl %edx
       cmpl %ecx,%edx
                                       Tail (T<sub>i</sub>)
        jl .L11
.L13:
```

Critical Section

 A critical section is a piece of code that accesses a shared resource (data structure or device) that must not be concurrently accessed by more than one thread of execution.

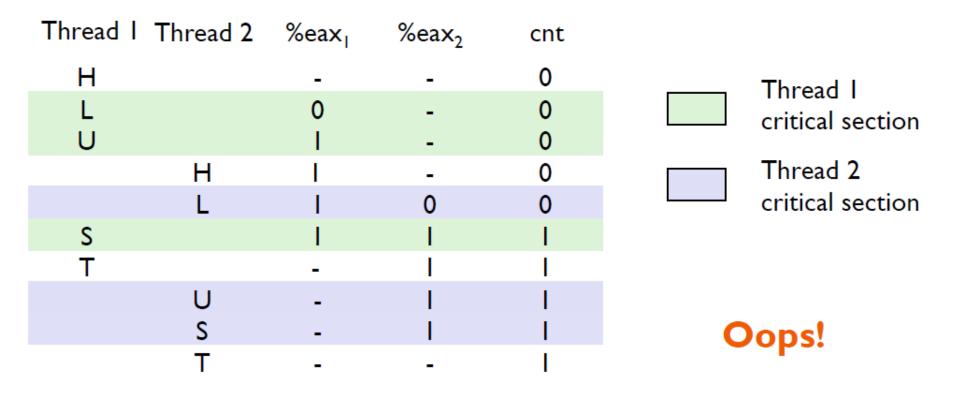
Assembly Code

• One possible ordering...



Assembly Code

• A second possible ordering...



```
int X = 0; /**< Global variable used for counting. */</pre>
/**
 * Increments global variable X by 1 a total of TOTAL times.
 */
void* count up( void *ptr )
{
       int i = 0;
       for (i=0; i < TOTAL; i++)
       { atomic { X++; } }
         /* atomic doesn't exist, how do we simulate it? */
       return NULL;
}
void main()
{
       pthread t tid[2]; int i;
       for (i=0; i<2; i++) {</pre>
              pthread create(&tid[i], NULL, count up, NULL); }
       for (i=0; i<2; i++) {</pre>
              pthread join(tid[i], NULL); }
```

printf("%d\n", X);

}

Mutex

• The pthread library provides us with a mutex, a variable that is "locked" or "unlocked".

- Key operation: pthread_mutex_lock()
 - When **locked**: wait until the variable is unlocked before locking and continuing.
 - When **unlocked**: lock the variable and continue.
- Also: pthread_mutex_unlock()

```
int X = 0; /**< Global variable used for counting. */
pthread mutex t mutex;
/**
 * Increments global variable X by 1 a total of TOTAL times.
 */
void* count up( void *ptr )
{
       int i = 0;
       for (i=0; i < TOTAL; i++) {</pre>
              pthread mutex lock(&mutex);
              X++;
              pthread mutex unlock(&mutex);
       }
       return NULL;
}
void main()
{
       pthread mutex init(&mutex, NULL);
       . . .
       pthread mutex destroy(&mutex);
}
```

In Hardware...

 Every system has a different way of implementing the atomic nature of pthread_mutex_lock().

```
• Fundamentally, we abstract it into a function that tests and sets a lock variable:
```

```
/**
 * A C-code representation of an atomic hardware instruction.
 *
 * If the value contained in lock is UNLOCKED (0), we LOCK (1) it
 * and return SUCCESS (0). If the value was LOCKED (1), we
* return FAILURE (1).
 *
 * In x86, this is done via an XCHG or LOCK optcodes.
*/
int testandset(int *lock)
{
      if (*lock == 0)  /* If our lock is unlocked... */
      {
             *lock = 1; /* ...lock it, */
             return 0; /* ...and return that we locked it. */
      }
      else
             return 1; /* Otherwise, we can't lock it. */
```

}

Two Terms in Synchronization

• **Mutual Exclusion**: At most, only one thread is accessing the critical section at any time.

 Progress: If a thread wants to enter the critical section and no other thread is in the critical section, it must have access to the critical section.

Violations in Synchronization

 Violation of Mutual Exclusion: At any time, two or more threads have access to the critical section.

 Violation of Progress: A thread is indefiniately blocked from entering the critical section when no other thread is executing the critical section.

Synchronization Examples

- In each example:
 - Assume x, x1, and x2 are initially set to 0.
 - Each thread may run any number of times, in any order.
 - One thread may finish before the other thread (eg: the system may only have one of the two threads executing after a period of time).

```
while (x > 0) { }
x++;
/* critical section */
x--;
```

Thread 2:

```
while (x > 0) { }
x++;
/* critical section */
x--;
```





```
while (x1 != 0) { }
x2 = 1;
/* critical section */
x2 = 0;
```

Thread 2:

```
while (x2 != 0) { }
x1 = 1;
/* critical section */
x1 = 0;
```





Thread 2:





Thread 1: if (x % 2 == 1) { /* critical section */ x = 2; }

Thread 2:

```
if (x % 2 == 0)
{
    /* critical section */
    x = 1;
}
```





while (x == 1) {}
x = 1;
/* critical section */

Thread 2:

while (x == 1) {}
x = 1;
/* critical section */





Thread 2:

```
while (testandset(&x)) { }
/* critical section */
x = 0;
```

while (testandset(&x)) { }
/* critical section */
x = 0;





```
Thread 1:
```

```
while (pthread_mutex_lock(&m))
    { }
    /* critical section */
pthread mutex_unlock(&m);
```

Thread 2:

```
while (pthread_mutex_lock(&m))
    { }
    /* critical section */
pthread_mutex_unlock(&m);
```

Mutual Exclusion?



Mutexes are limited...

- How do we allow two threads to enter a code region (as opposed to 1)?
- How do we allow the same thread to enter a code region multiple times (but not any other threads)?
 - Equivalent to the **synchronized** keyword in Java.
- How do we allow any general condition?

Conditional Variables

- Idea:
 - Any number of threads can _wait() for a condition.
 - When the condition has changed, the thread changing the condition _signal()s one thread or _broadcast()s to all the threads.
 - The condition itself is contained a critical section, allowing only one thread to access it.

pthread_cond_wait()

- In pthread_cond_wait():
 - Takes two arguments:
 - **pthread_cond_t**: The conditional variable.
 - pthread_mutex_t: The mutex for the critical section.
 - When pthread_cond_wait() is called:
 - Unlocks the mutex, (so the mutex must be locked)
 - Waits for a signal, (via _signal() or _broadcast())
 - Locks the mutex before running again

Conditional Variables

- Scenario #1:
 - Block all threads until at least four threads arrive.
 Upon the fourth thread, allow all threads (blocked and future) to continue.

```
pthread_mutex_t mutex; /* _mutex_init() called elsewhere */
pthread_cond_t cond; /* _cond_init() called elsewhere */
int threads_seen = 0;
void roadblock_four()
{
    pthread_mutex_lock(&mutex);
    threads_seen++;
    pthread_cond_broadcast(&cond);
    while ( threads_seen < 4 )
        pthread_cond_wait(&cond, &mutex);
    }
}</pre>
```

```
pthread_mutex_unlock(&mutex);
```

}

Conditional Variables

• Scenario #2:

- Create a blocking queue data structure.

Any operation to _dequeue() should block until data is available.

```
typedef struct blockingqueue t
{
        queue t *q; /* Standard queue. */
        pthread mutex t mutex;
        pthread cond t cond;
} blockingqueue t;
void *blockingqueue dequeue(blockingqueue t *q)
{
        pthread mutex lock( &(q->mutex) );
        while (queue size(q - > q) == 0)
                 pthread cond wait( &(q->cond), &(q->mutex) );
        void *ret = queue dequeue( q->q );
        pthread mutex unlock( &(q->mutex) );
        return ret;
}
void blockingqueue enqueue(blockingqueue t *q, void *item)
{
        pthread mutex lock( &(q->mutex) );
        queue enqueue (q->q, item);
        pthread cond signal( &(q->cond) );
        pthread mutex unlock( &(q->mutex) );
}
```